

Digital assist / enhancement for ADCs and DACs

DAT116, Dec 20 2018
larssv@chalmers.se

Recap slide

E_{ADC} VS E_{NAND}

SNDR (dB)	E_{ADC}	$E_{\text{ADC}} / E_{\text{NAND}}$
30	21 nJ	4700
50	168 nJ	38000
70	1.35 μ J	300000
90	10.8 μ J	2400000

- Complete ADC energy per conversion (in 2008) vs energy of one NAND-gate logic transition in 90-nm CMOS
- Digital logic more “affordable” for higher resolutions!
 - Even more in newer technologies
- Increasingly attractive to use digital methods to improve performance!

Assist? Enhancement?

- Techniques that rely on more-or-less complex digital techniques to improve converter performance
 - Every sample and/or on average
- Calibration
- Redundant pipelined ADCs
- Interleaved ADCs
- Dynamic element balancing in DACs
- $\Sigma\Delta$ ADCs, DACs

Improving every sample

Calibration

- Adjust “translation table” from analog to digital data (or conversely) to reduce errors
- Main focus typically on INL errors
 - Large-scale errors cancelled using a few polynomial coefficients
- Two main categories of calibration:
 - Foreground / offline
 - Background / online

Foreground calibration

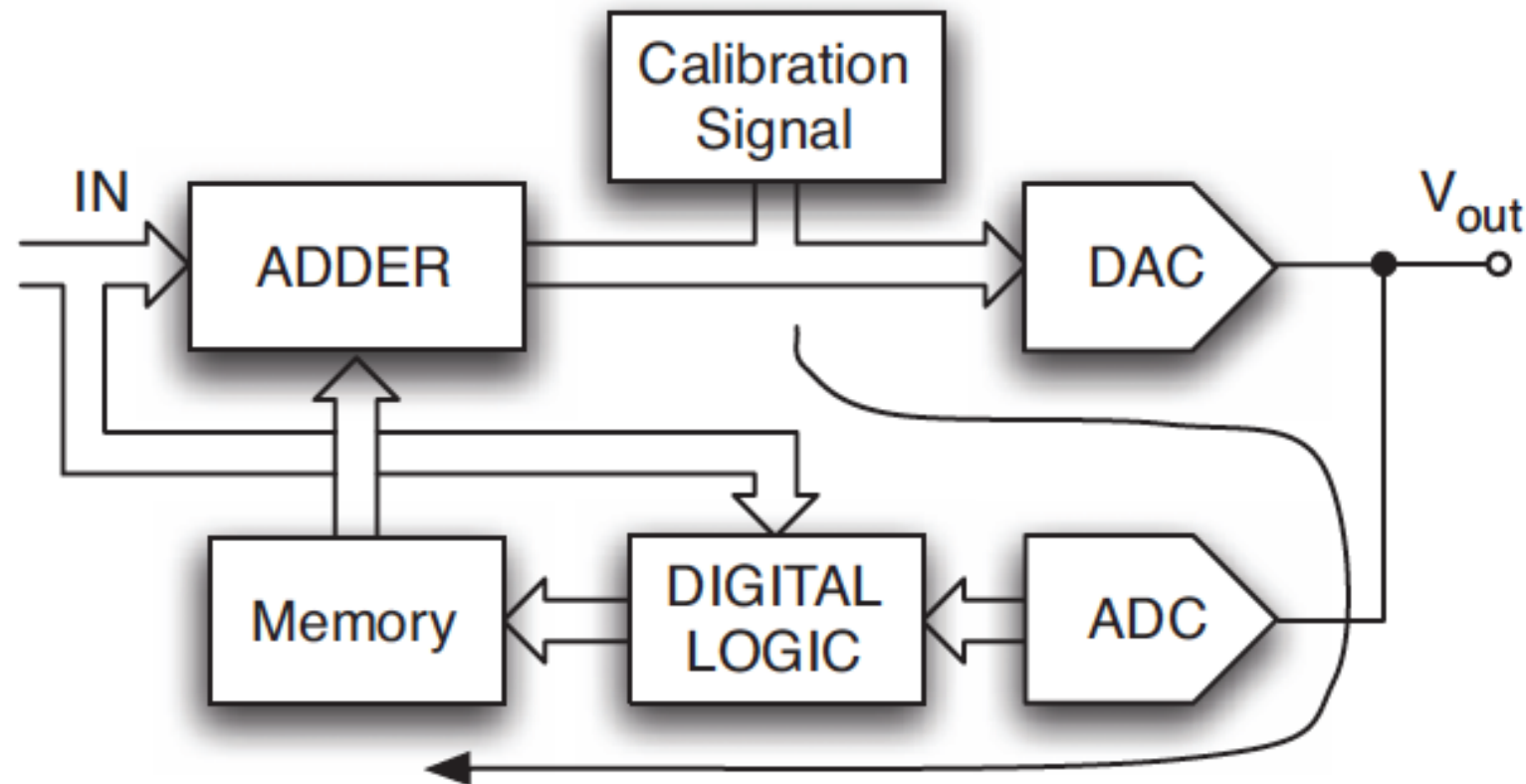


Figure 8.6. Conceptual scheme of a foreground calibrated DAC.

- Apply known calibration signal as input
- Observe output, compare with expected value
- Adjust “on digital side”

Background ADC calibration

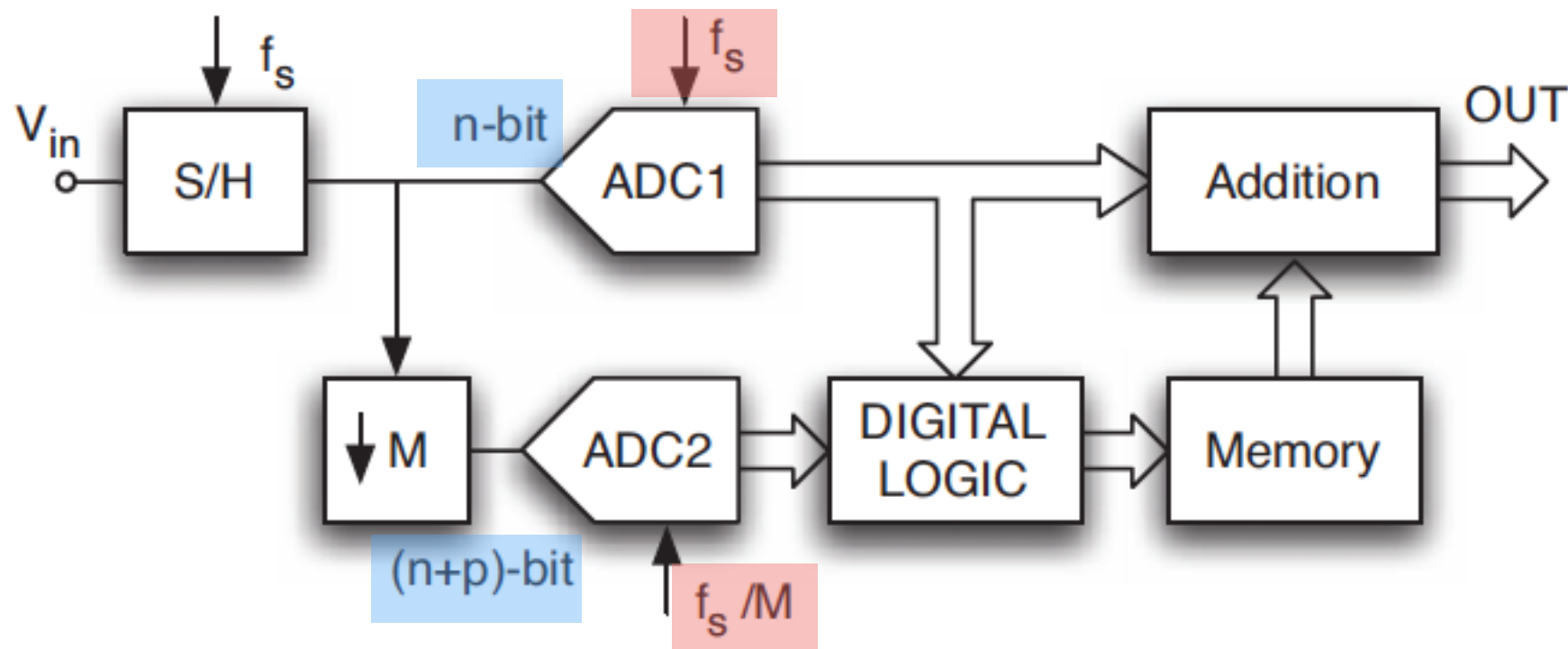
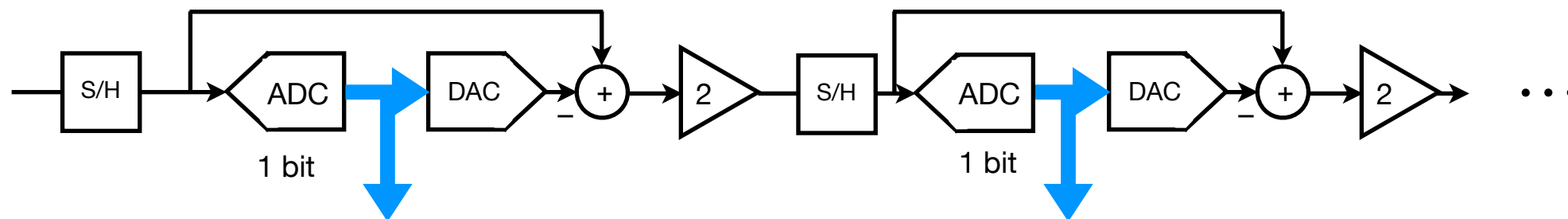


Figure 8.8. Calibration with a slow high-resolution converter.

- Auxiliary converter (ADC2) for calibration only
- Higher accuracy, but slower
- An example; other methods possible

1-bit pipelined ADC



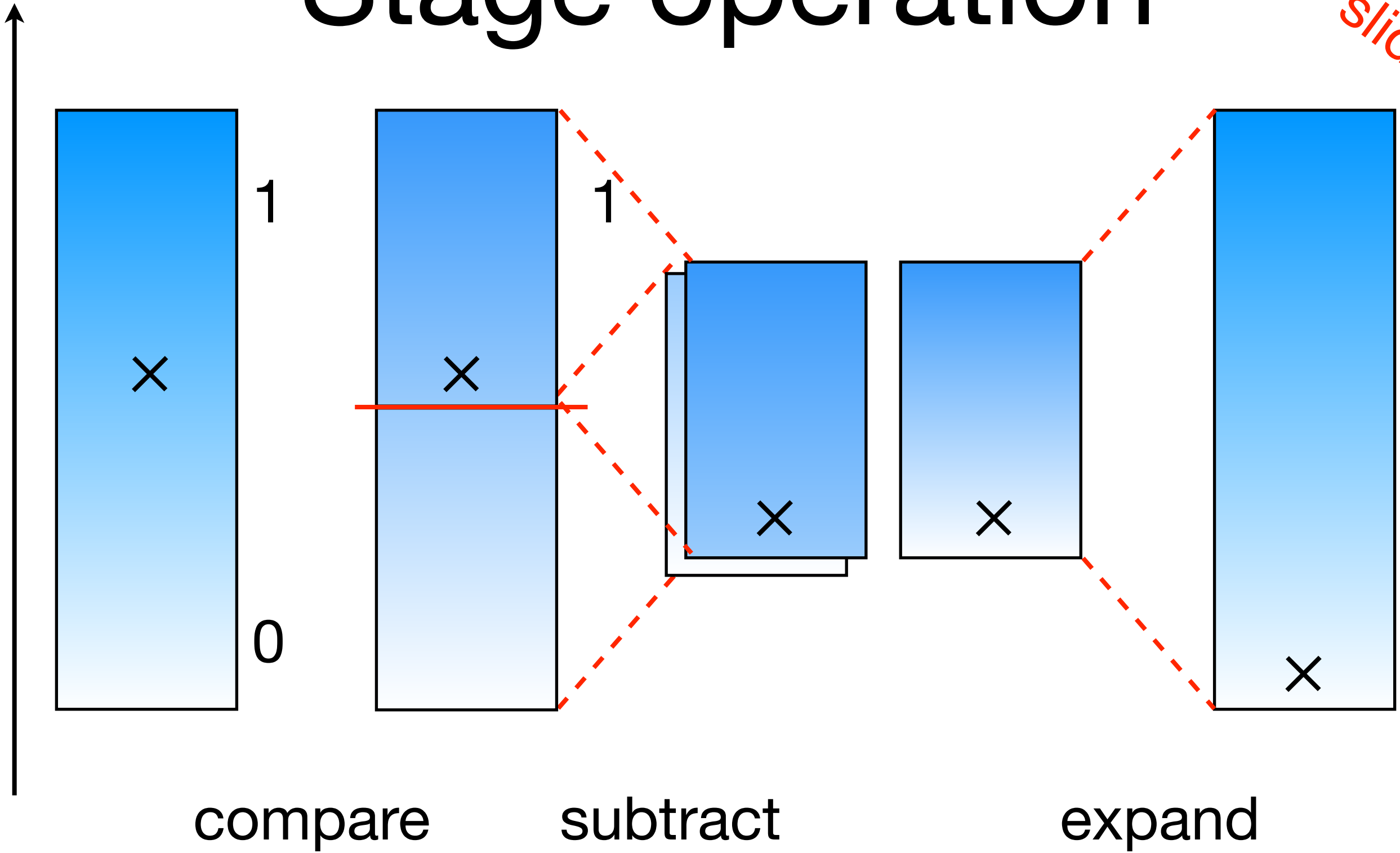
- Decide on MSB (i.e., make a 1-bit AD conversion)
- Convert bit back to analog
- Subtract from original value
- Multiply residual by 2
- Repeat for next bit, etc.

Add redundancy
for error correction!

Stage operation

Recap slide

voltage

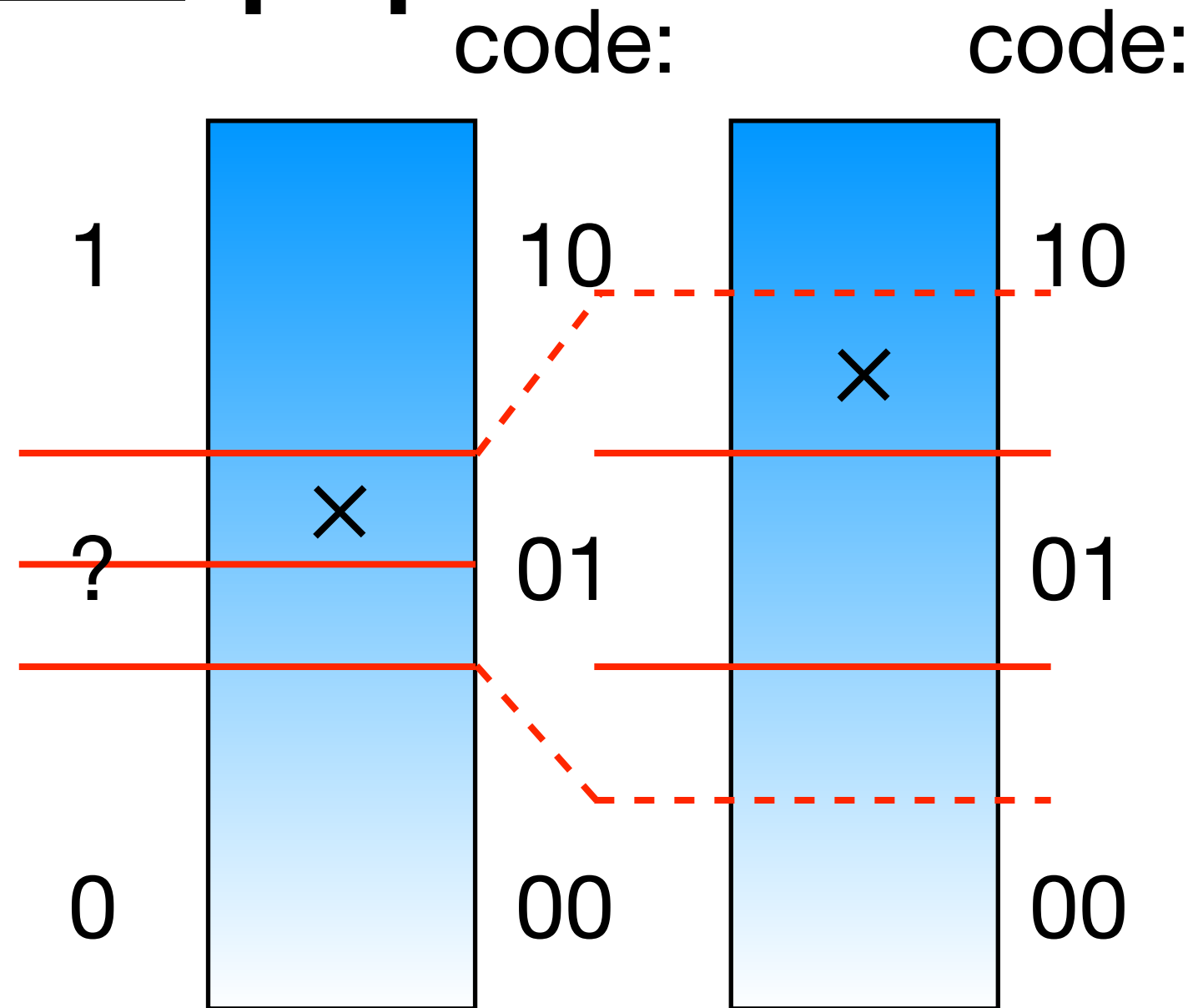


$\pm 1/4$ of full range

x2

Redundant pipeline

- Idea: postpone bit decision if value close to border!
- If so, don't subtract anything, just expand
 - Now value farther from border!
- Look again after next gain stage
- Smart codes make calculation of final value trivial



0 1
1 0
1 0 0

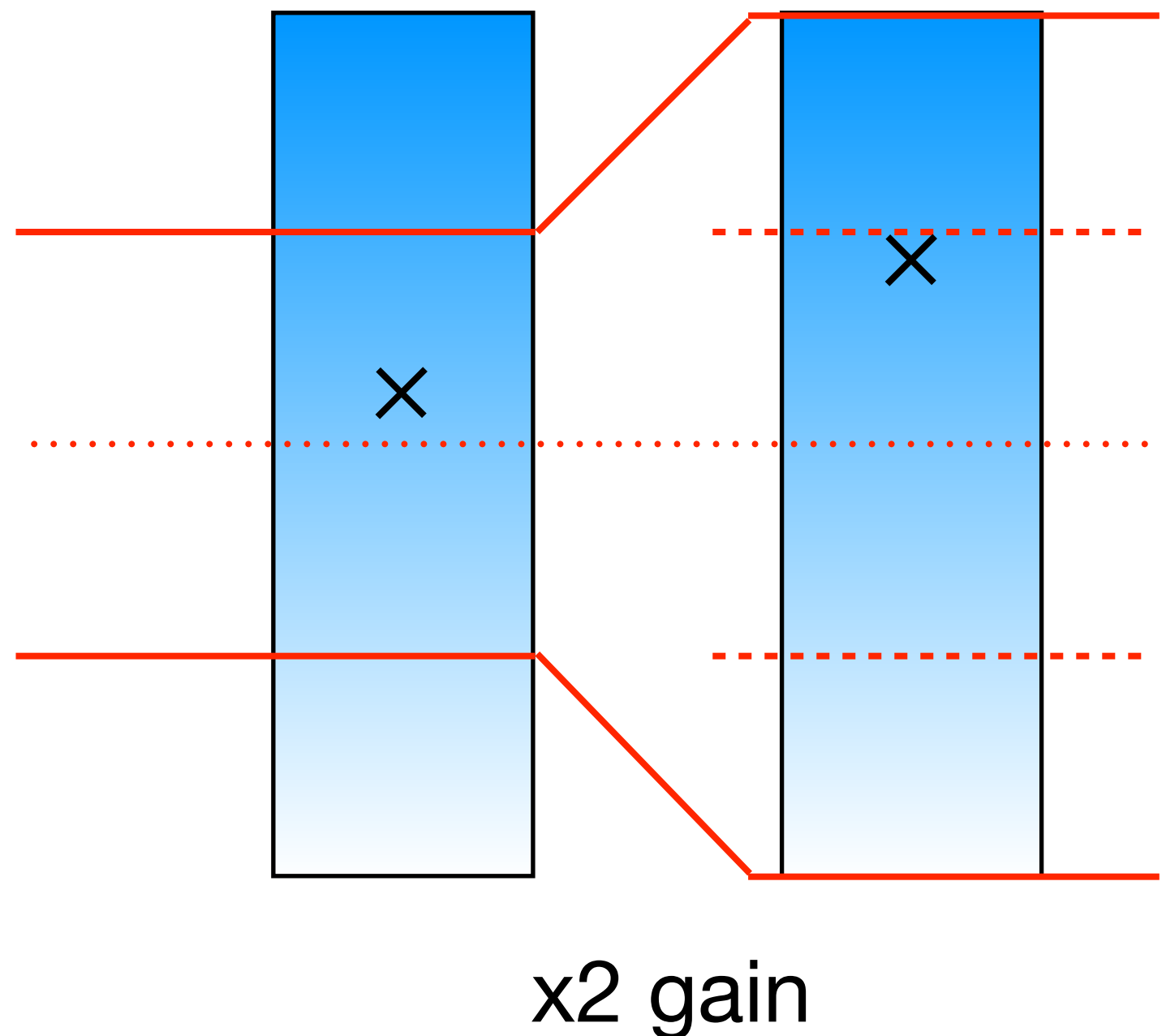
Addition!

Redundant pipeline

- Redundancy: two decisions, eventually one bit
- Two comparators / decision levels per stage
 - Still no nonlinearity!
 - Gain, offset errors
- “1.5 bits”
 - Between 1 bit and 2 bits :-/
- No redundancy in last stage
 - Cannot be corrected since no next stage!
- Typically 1 or 2 bits in last stage

Limits?

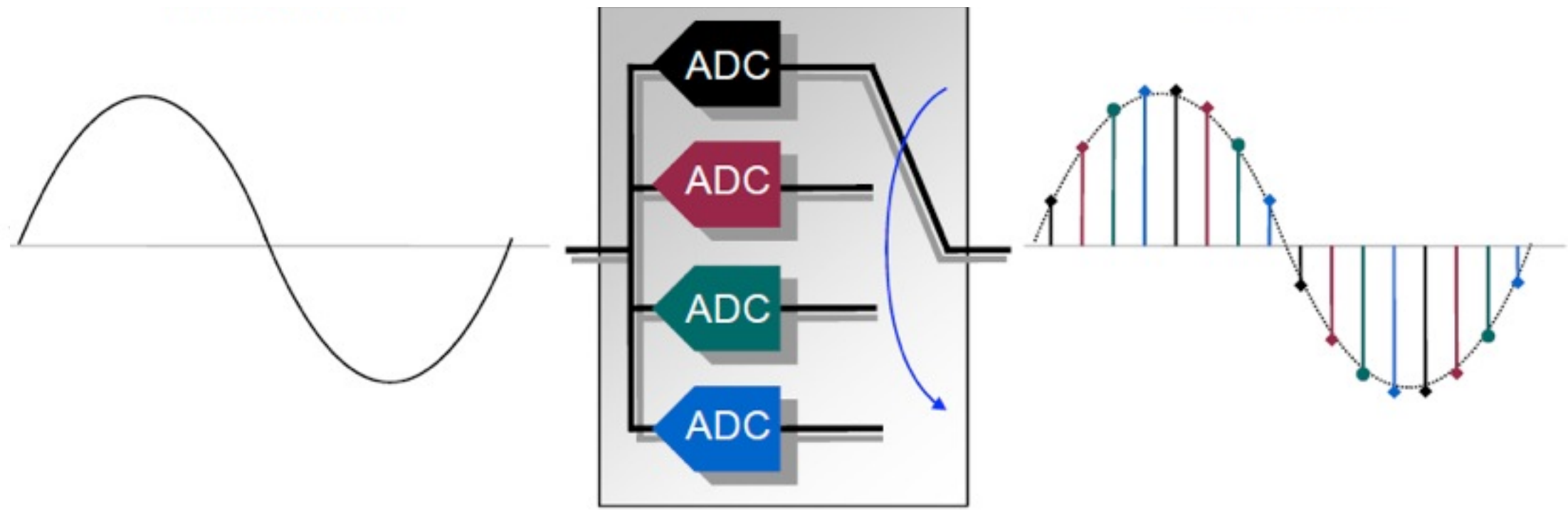
- Delay decision for all values less than half of full swing!
- Allows very large decision errors ($\pm V_{FS}/4$)
- Very simple comparator sufficient
- 2nd delayed decision means 2-step carry in addition (etc)



Benefits/drawbacks

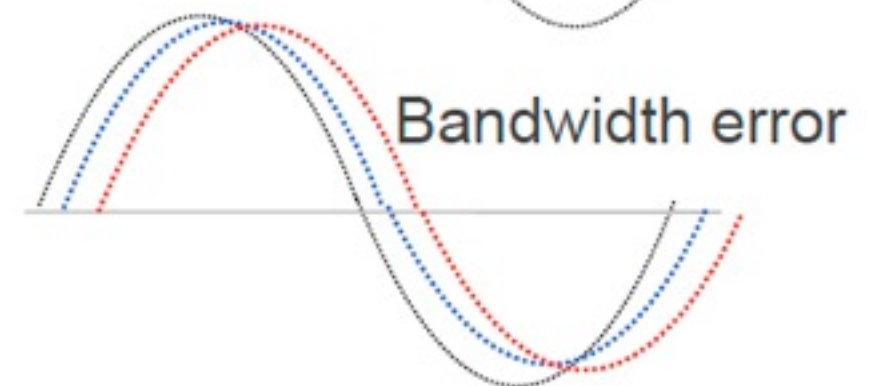
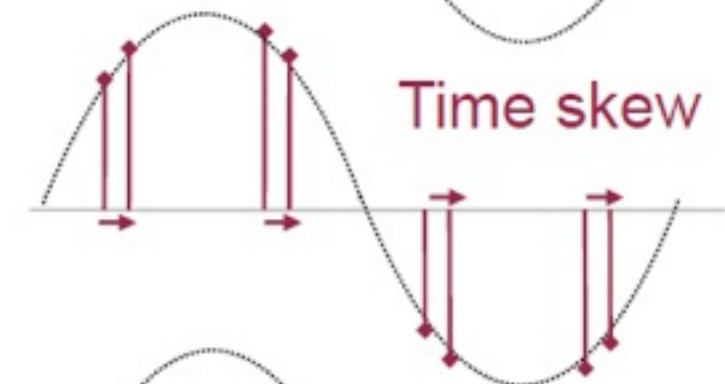
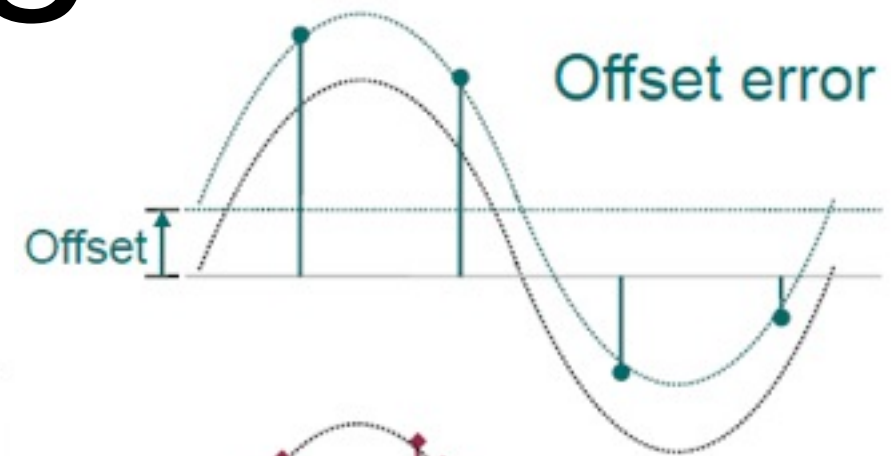
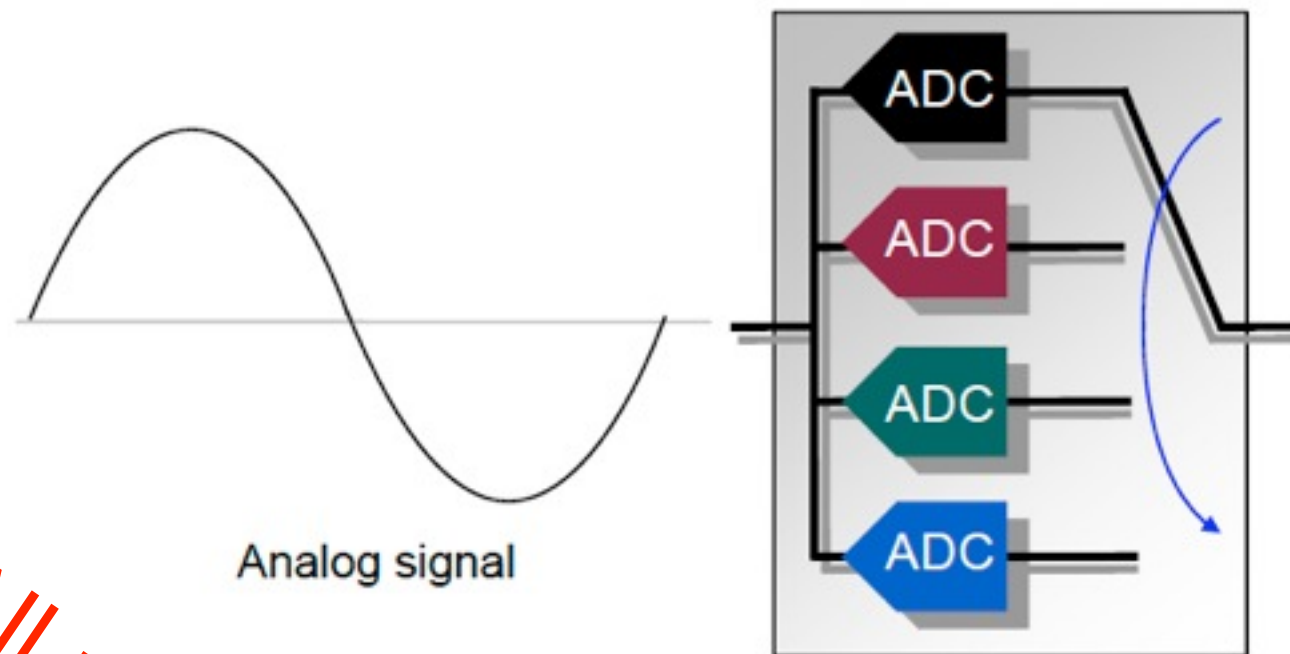
- + One bit per stage, so #stages $\sim N$
- + Very insensitive to offsets
- + High sample rates
- + Simple digital parts
- Still depends on accurate x2 amplifier
- Latency

Time-interleaved ADC



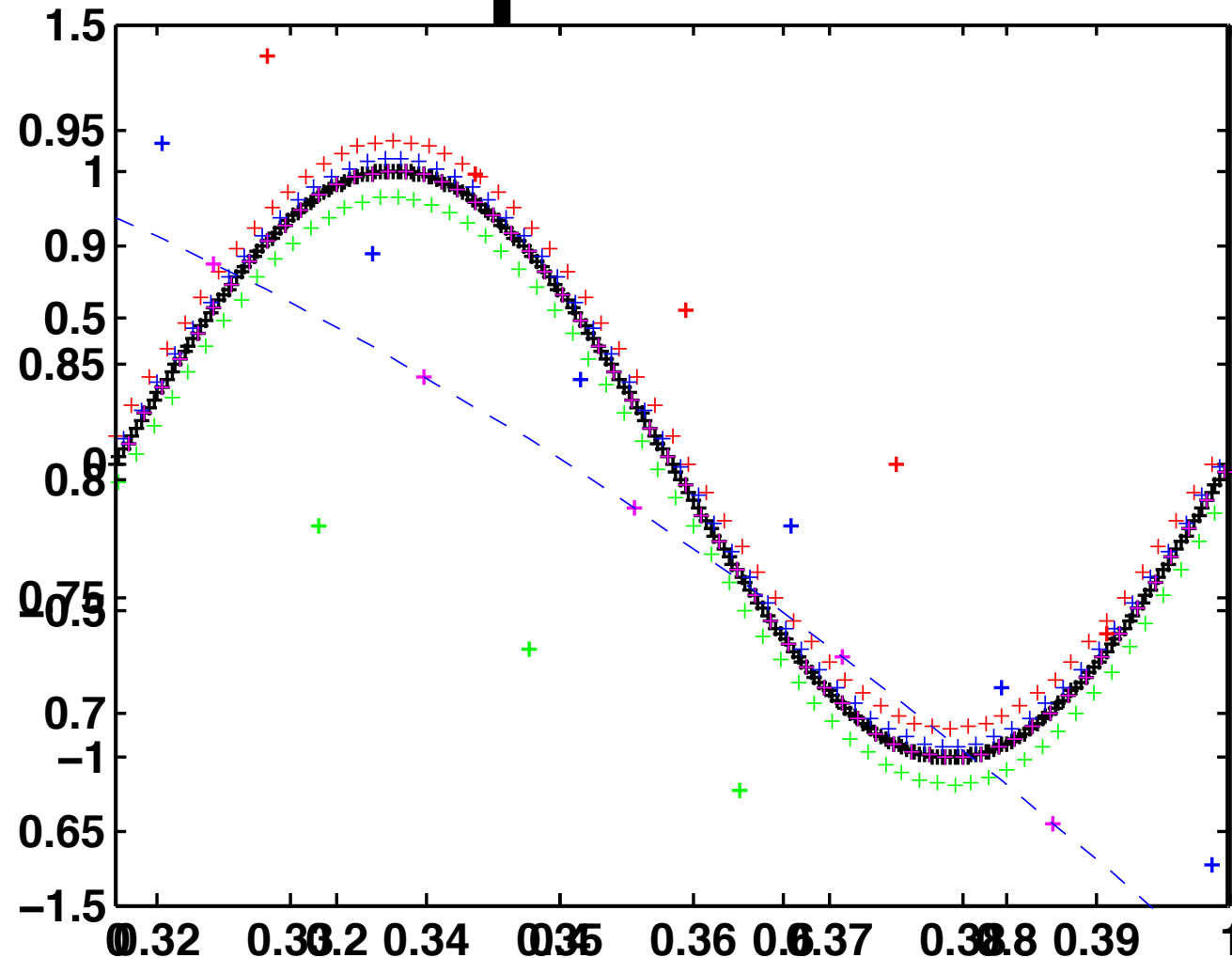
- N (here: 4) parallel ADCs, each at f_s
- Round-robin sampling @ N times f_s
- Problem: ADCs not identical in practice
 - Systematic errors of several kinds

Interleaving errors



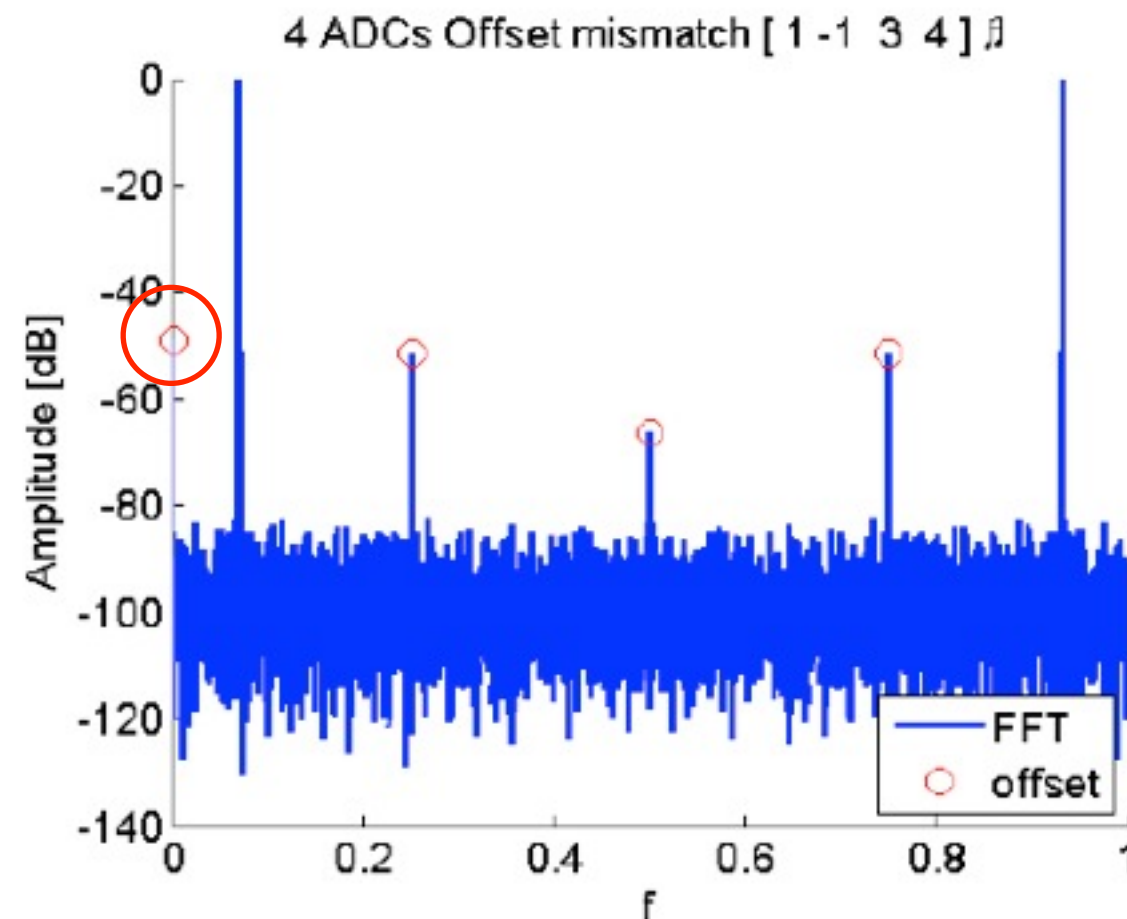
All possible to handle.

Example: offsets



- Offset of each ADC path affects sampled and converted values
- Repeating sequence of offset values added to signal
 - ... O₁ O₂ O₃ O₄ O₁ O₂ ...

Offsets in spectrum

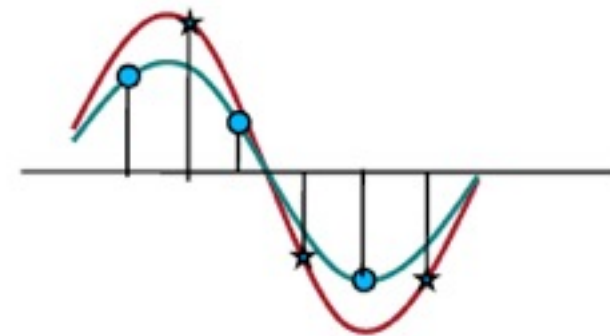


- In spectral domain, will show as spur components at $n \cdot f_s/N$, $n = 0 \dots N - 1$
- Note: spur frequencies unrelated to signal frequency!
 - Occur also with no input signal!

Example: gain error

- Two paths:

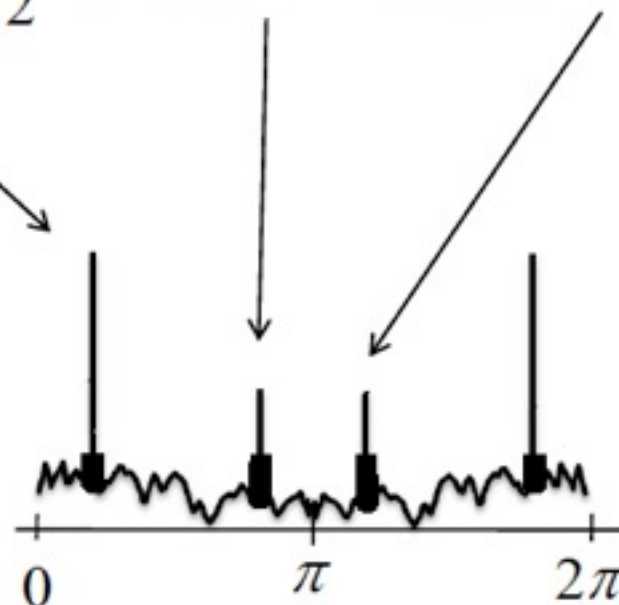
$$s(nT) = \begin{cases} A_1 \sin(\omega nT) & n \text{ even} \\ A_2 \sin(\omega nT) & n \text{ odd} \end{cases}$$



$$s(nT) = (\alpha + \beta \cos(\pi n)) \cdot \sin(\omega nT)$$

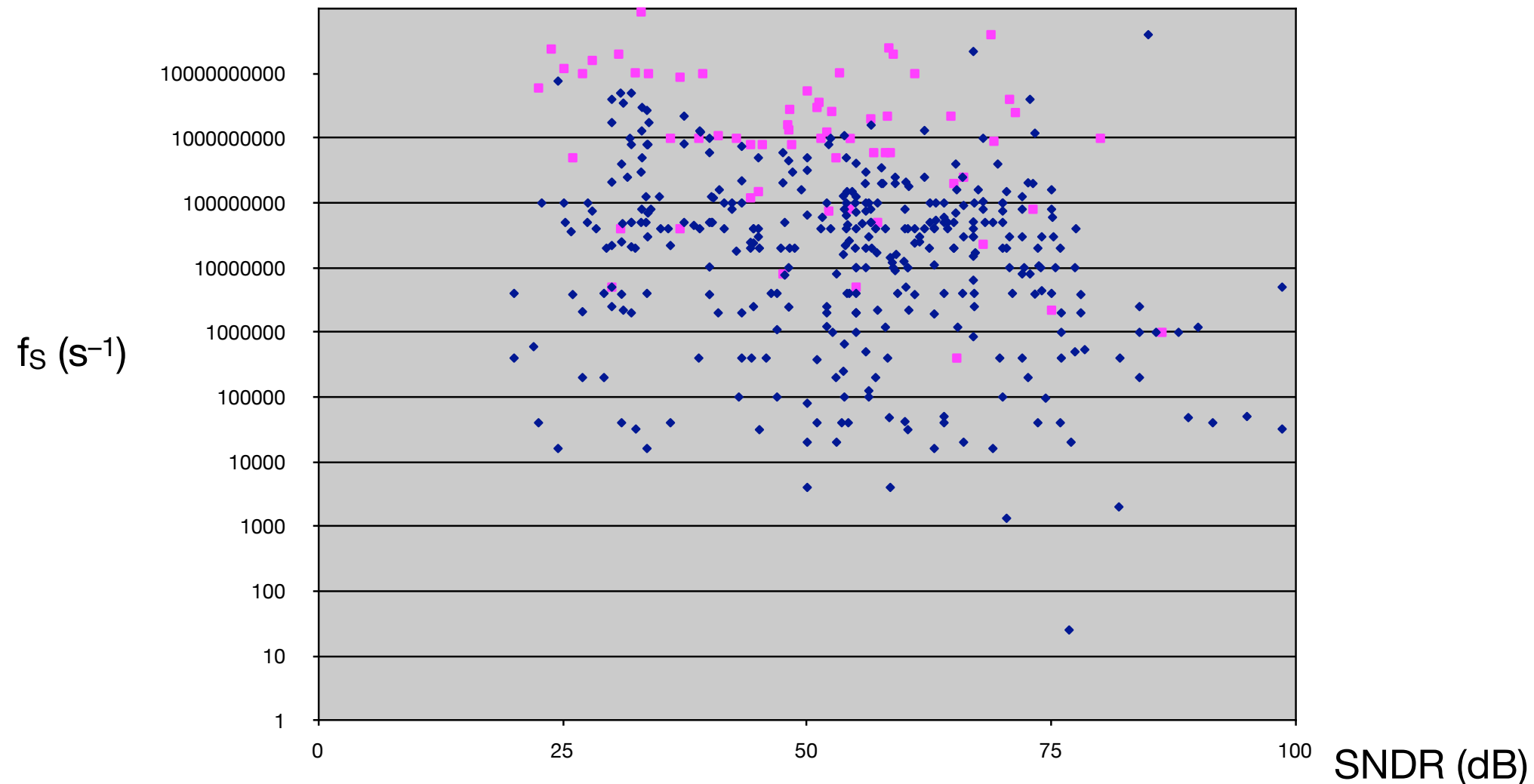
± 1

$$s(nT) = \alpha \cdot \sin(\omega nT) + \frac{\beta}{2} \cdot (\sin((\omega T - \pi) \cdot n) + \sin((\omega T + \pi) \cdot n))$$



spurs centered
around $f_s/2$
depend on
input f

When useful?



- Magenta dots for time-interleaved converters
- High sample rates regardless of SNDR

Why use interleaving?

- Increase sample rate!
 - Possibly by factor N with N converter paths
- Improve speed/power relation
 - Choose more frugal architecture for substituent path converters
 - Hope for less than $N \cdot (1/N)$ overall power
 - Digital correction circuitry is “free” 😊

Literature

First publication

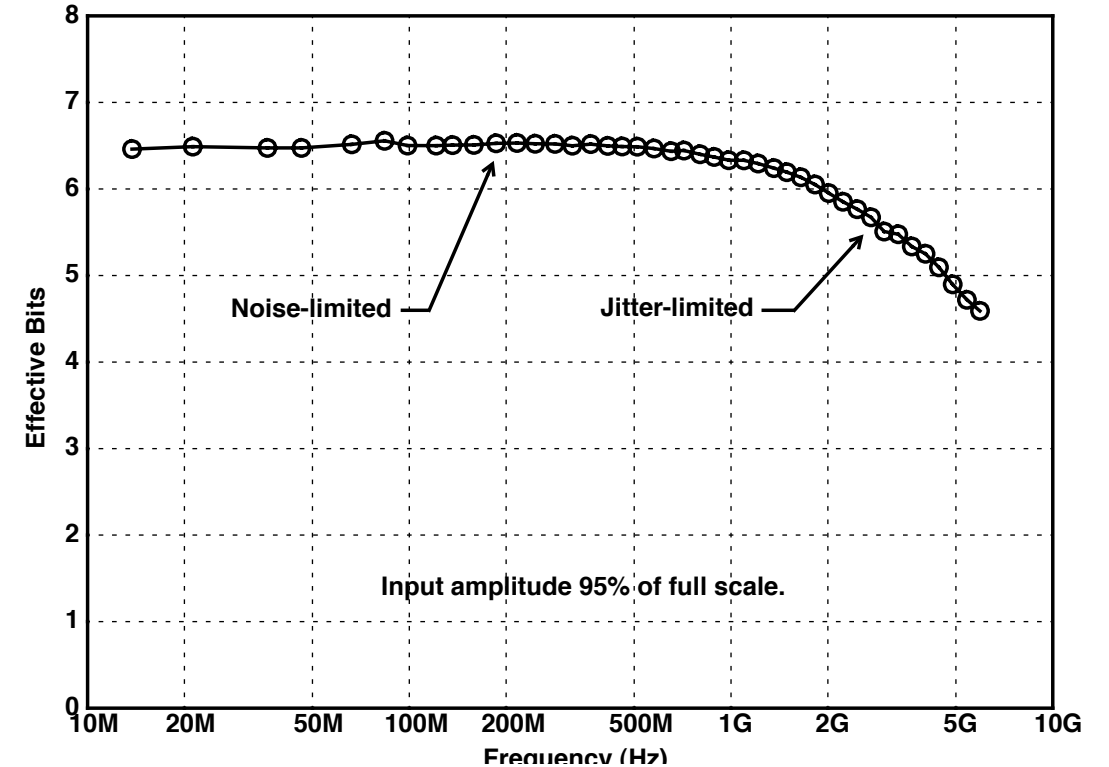
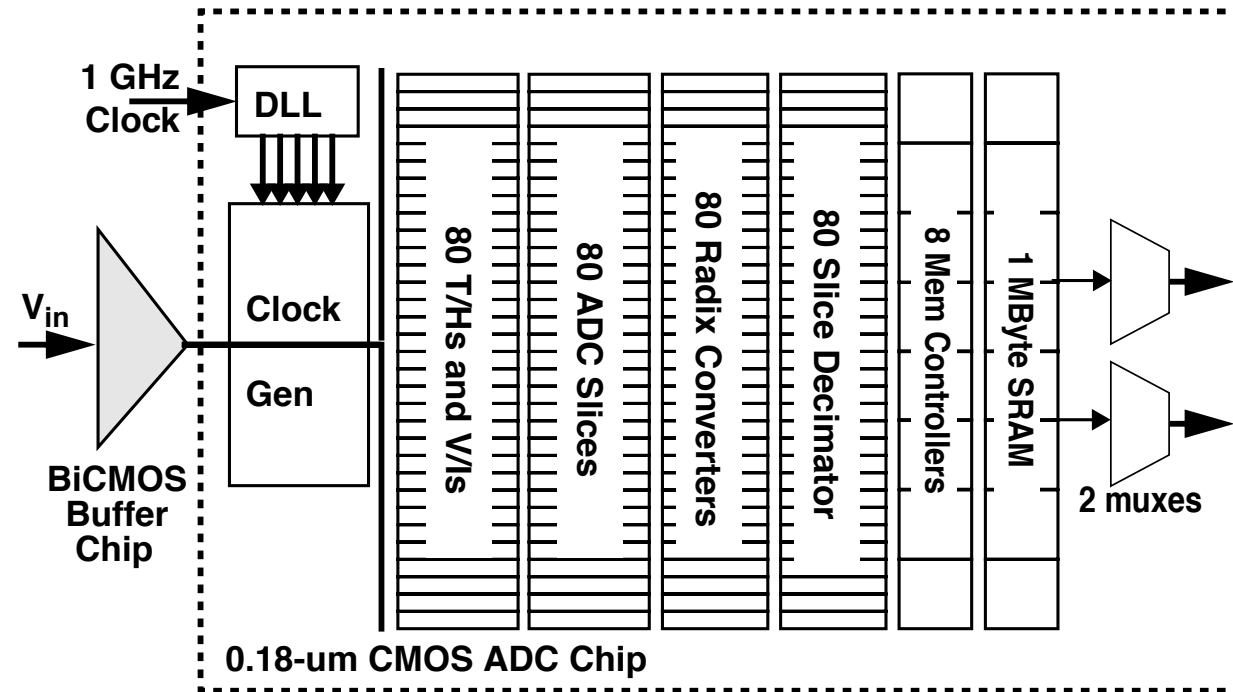
- W. C. Black Jr. and D. A. Hodges, "Time Interleaved Converter Arrays," IEEE International Conference on Solid State Circuits, Feb **1980**, pp. 14–15.

Examples!
Use IEEEExplore!
Prof. Murmann's data!

ISSCC2008 typical paper references:

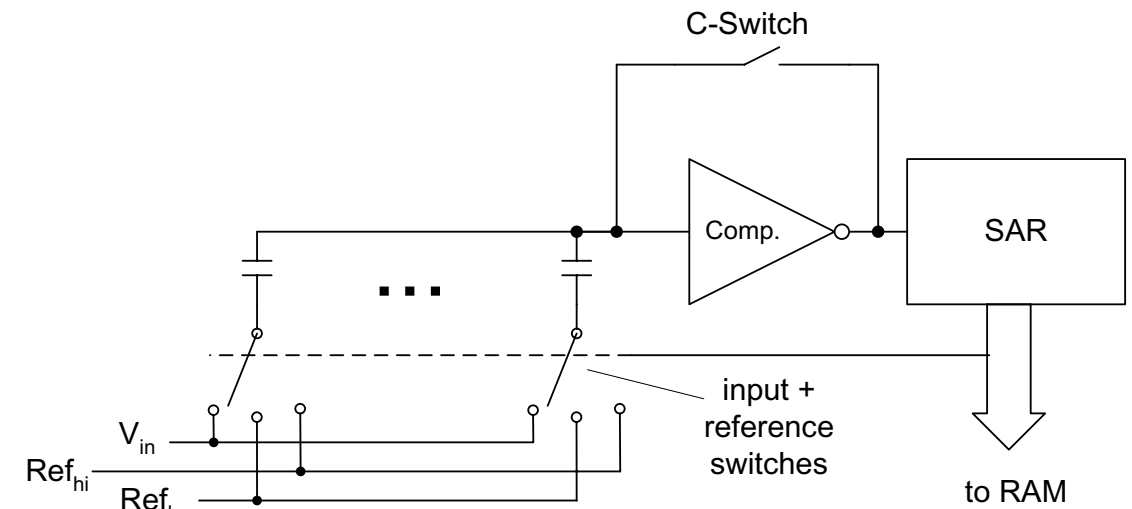
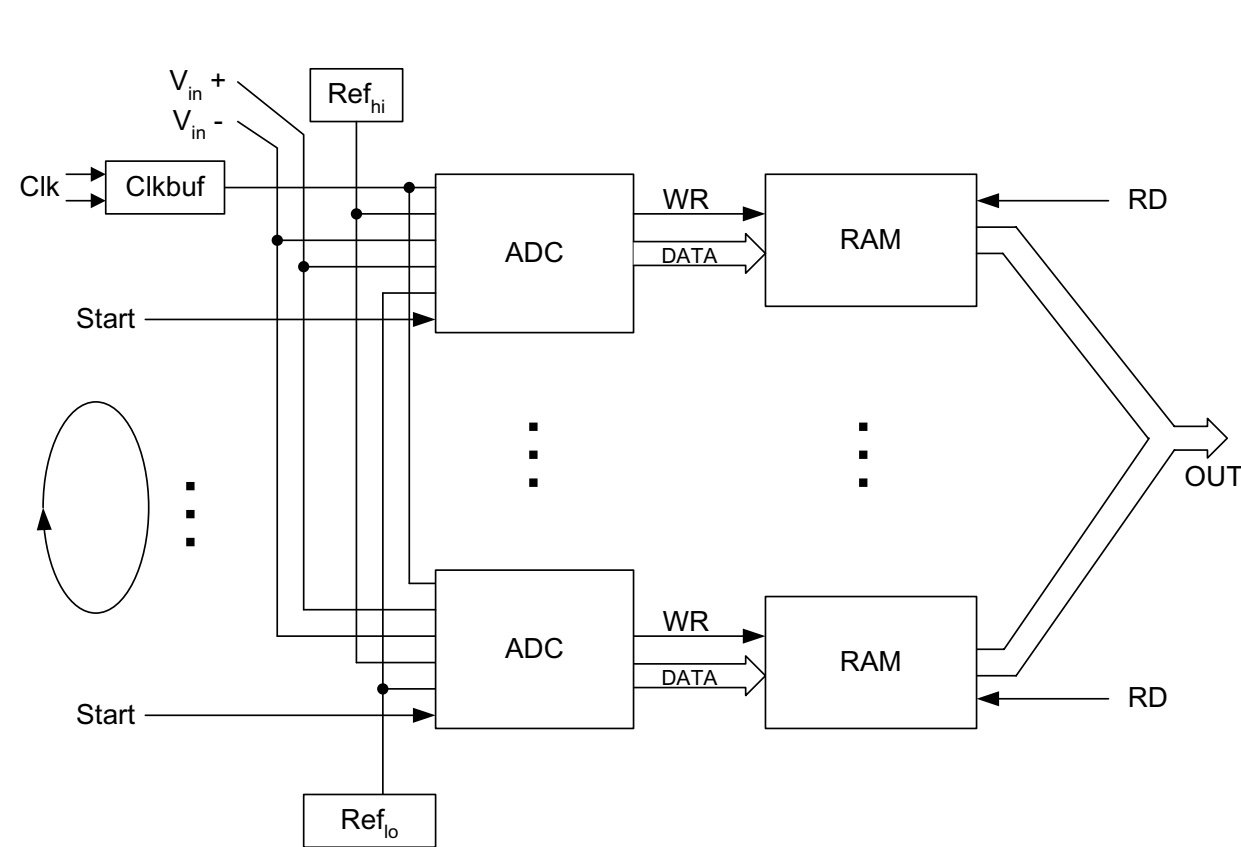
- [1] K. Poulton, R. Neff, B. Setterberg, et al., "A 20 GS/s 8 b ADC With a 1 MB Memory in 0.18 μ m CMOS," *ISSCC Dig. Tech. Papers*, pp. 318-319, Feb. **2003**.
- [2] S. Gupta, M. Inerfield, and J. Wang, "A 1-GS/s 11-bit ADC With 55-dB SNDR, 250-mW Power Realized by a High Bandwidth Scalable Time-Interleaved Architecture," *IEEE J. Solid-State Circuits*, vol. 41, pp. 2650-2657, Dec. **2006**.
- [3] D. Draxelmayr, "A 6b 600MHz 10mW ADC Array in Digital 90nm CMOS," *ISSCC Dig. Tech. Papers*, pp. 264-265, Feb. **2004**.
- [4] B. P. Ginsburg and A. P. Chandrakasan, "500-MS/s 5-bit ADC in 65-nm CMOS With Split Capacitor Array DAC," *IEEE J. Solid State Circuits*, vol. 42, no. 4, pp. 739-747, Apr. **2007**.

Poulton 2003



- 80 interleaved 12-stage pipelined ADCs
- 1.5 bits / stage, reduced to 8 bits w/ corrections
- 8 bits @ 20 GS/s, ≤ 6.5 ENOB
- 1 W (buffer) + 9 W (ADC) = 10 W

Draxelmayr 2004



- 6b, 8-way interleaved
- SAR sub-converters
- 10 mW @ $f_s = 600$ MHz

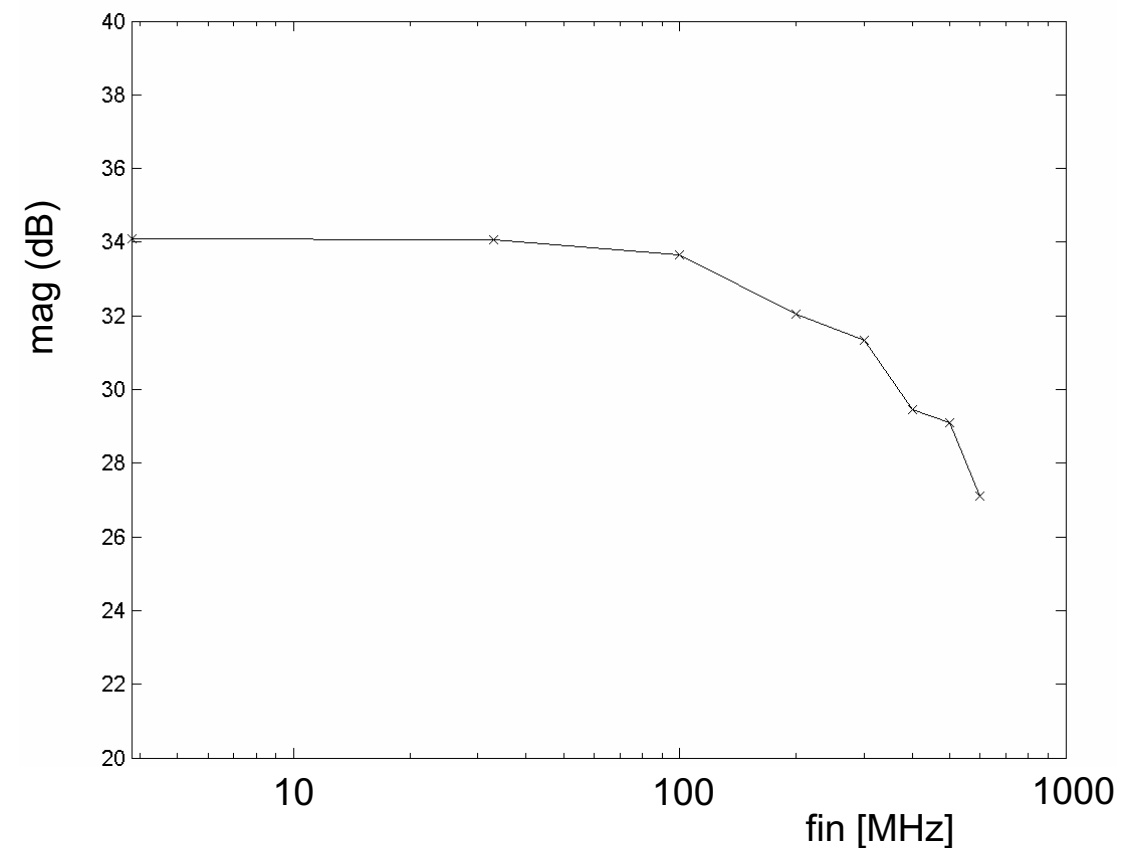
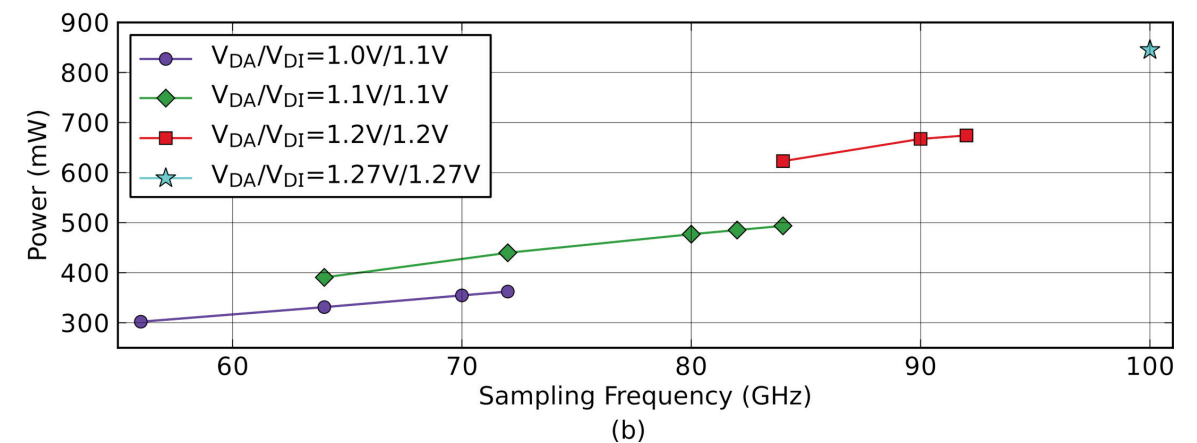
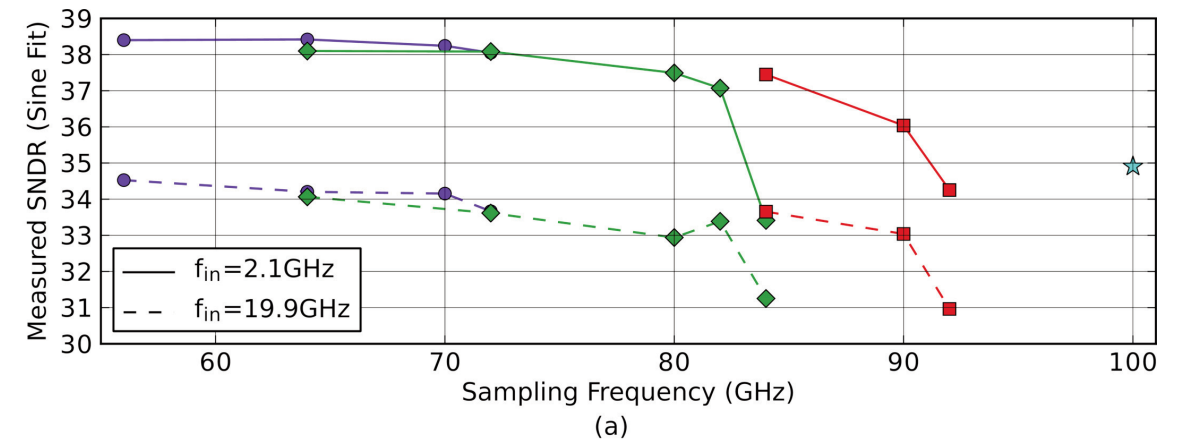
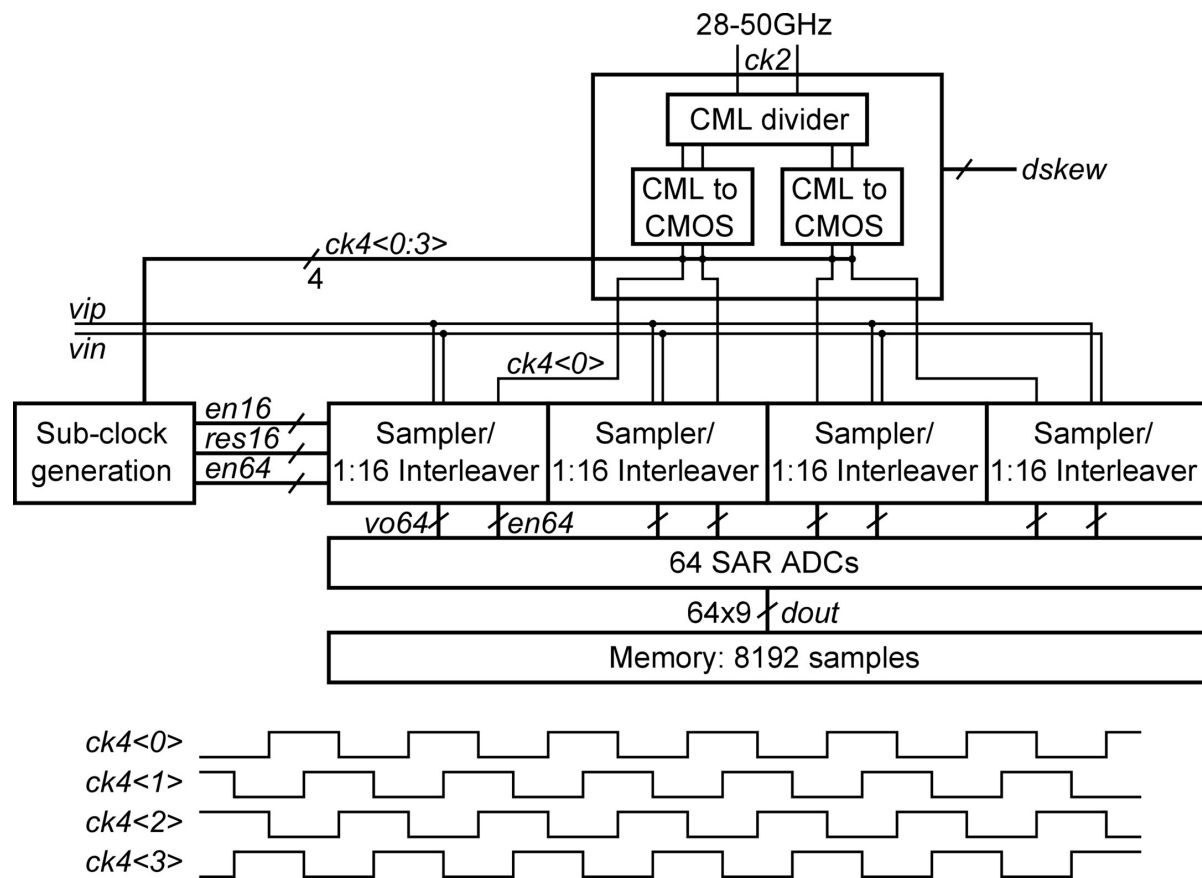


Figure 14.7.6: SINAD vs. f_{in} at $f_c=600$ MHz (offset corrected).

Kull 2014

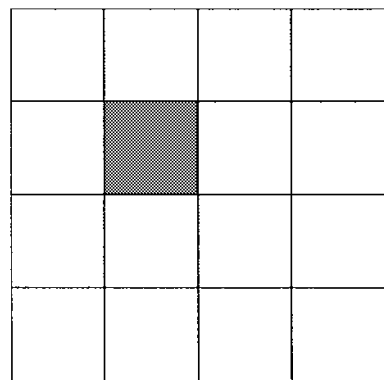


- 90 GS/s, 8b, 667 mW
- 64 SAR sub-converters
- Current world record for ADC sample rate

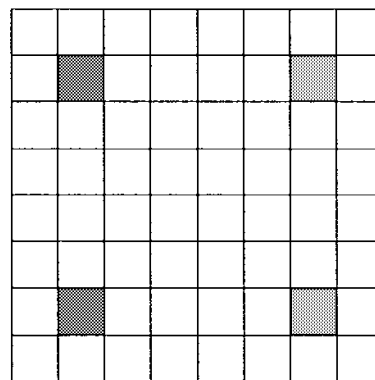
Improving on average

D/A converter errors

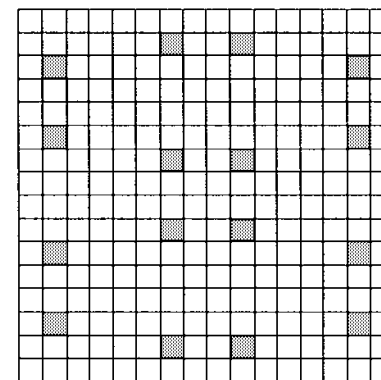
- Thermometer-coded, unary-scaling current-source D/As very popular
 - Large number of sources (2^N)
 - Large area
 - Mfg gradient errors cause harmonics
- Improve matching with common-centroid layouts
 - Split sources in groups with common center
 - More switches, etc



(a)



(b)



(c)

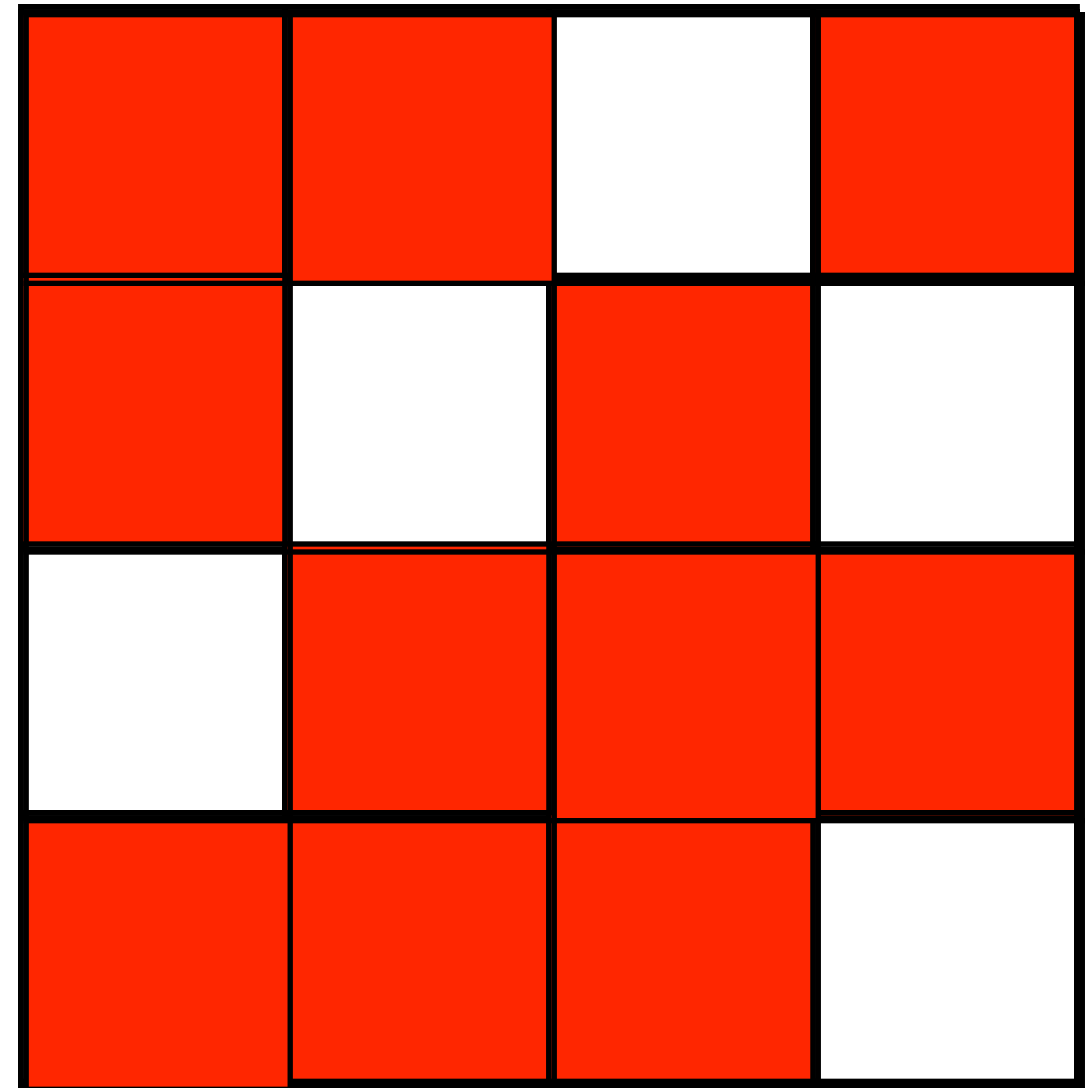
[Van der Plas 1999]

Errors vs distortion

- Remaining INL/DNL will cause harmonic distortion of sinewave input
 - Spurious tones in output
 - Often undesirable (depends on application)
- INL/DNL diagrams show the error at each output value
 - Error is well-defined since always the same set of current sources (with same set of deviations) for same converted value

Randomization

- Idea: use different set of sources for each conversion!
- Select e.g. by pseudo-random sequence
- “Dynamic element matching”
- Distortion -> noise
- Better SFDR!
- Esp. useful for feedback DACs in $\Sigma\Delta$ ADCs



[L. R. Carley. Noise-shaping coder topology for 15+ bit converters. IEEE Journal of Solid-State Circuits, April 1989]

Poulton 2011

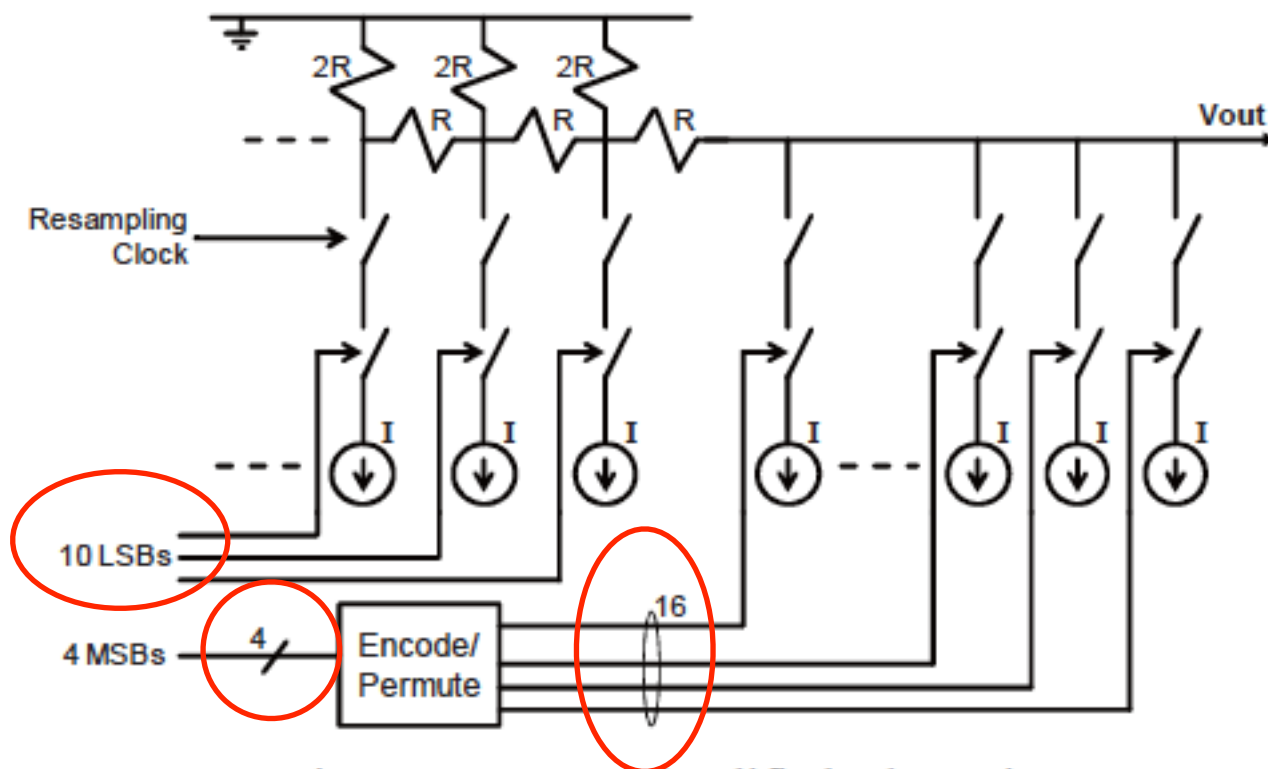


Fig. 1 DAC Core simplified schematic

- 14b, 7.2 GS/s
- Unary scaling for 4 MSBs, binary scaling for the rest
 - MSBs randomized
- SFDR ~10 dB better than comparable DACs
- 4.6 W (ugh)

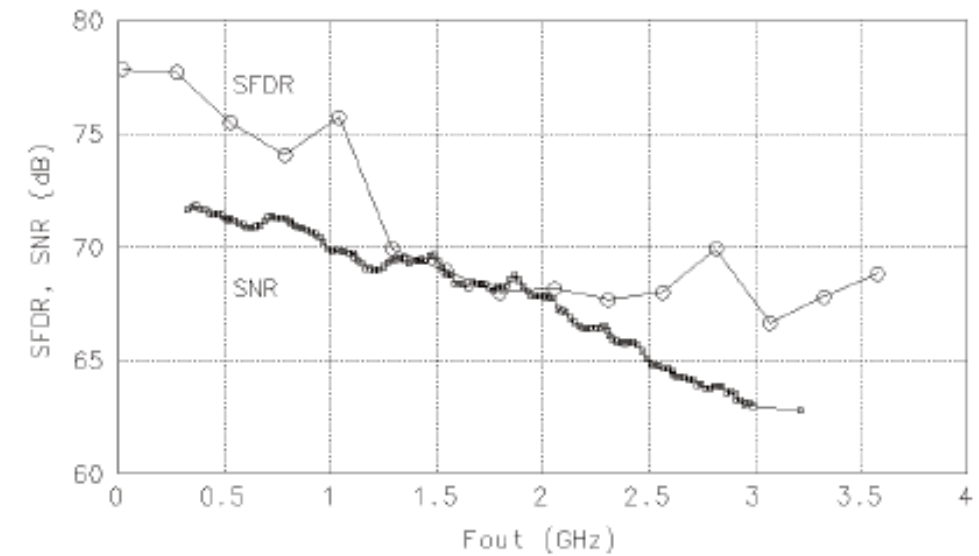


Fig. 5 SFDR (including harmonics) and SNR vs. Fout at 7.2 GSa/s

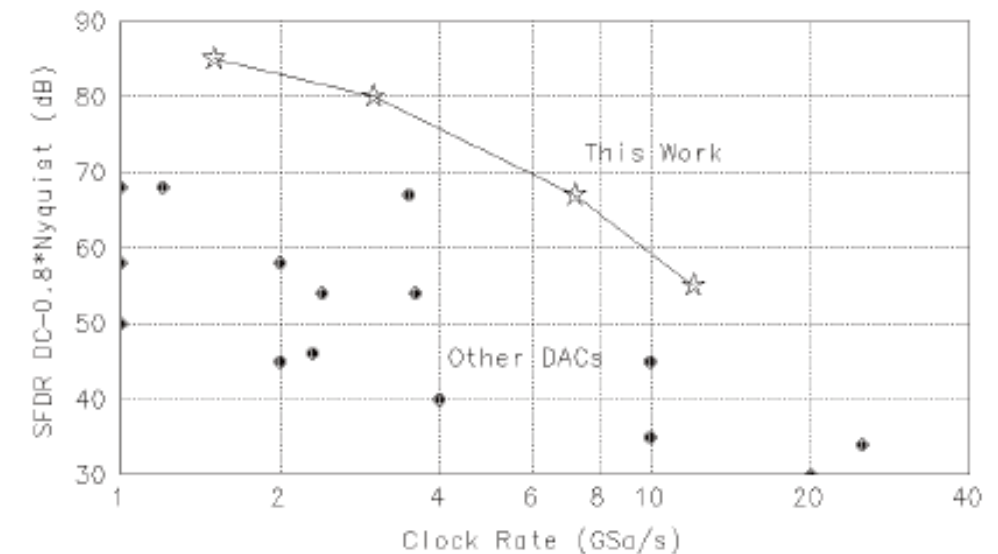


Fig. 6 SFDR over Nyquist vs clock rate for this DAC and other DACs (published papers and datasheets)

“De-randomization”

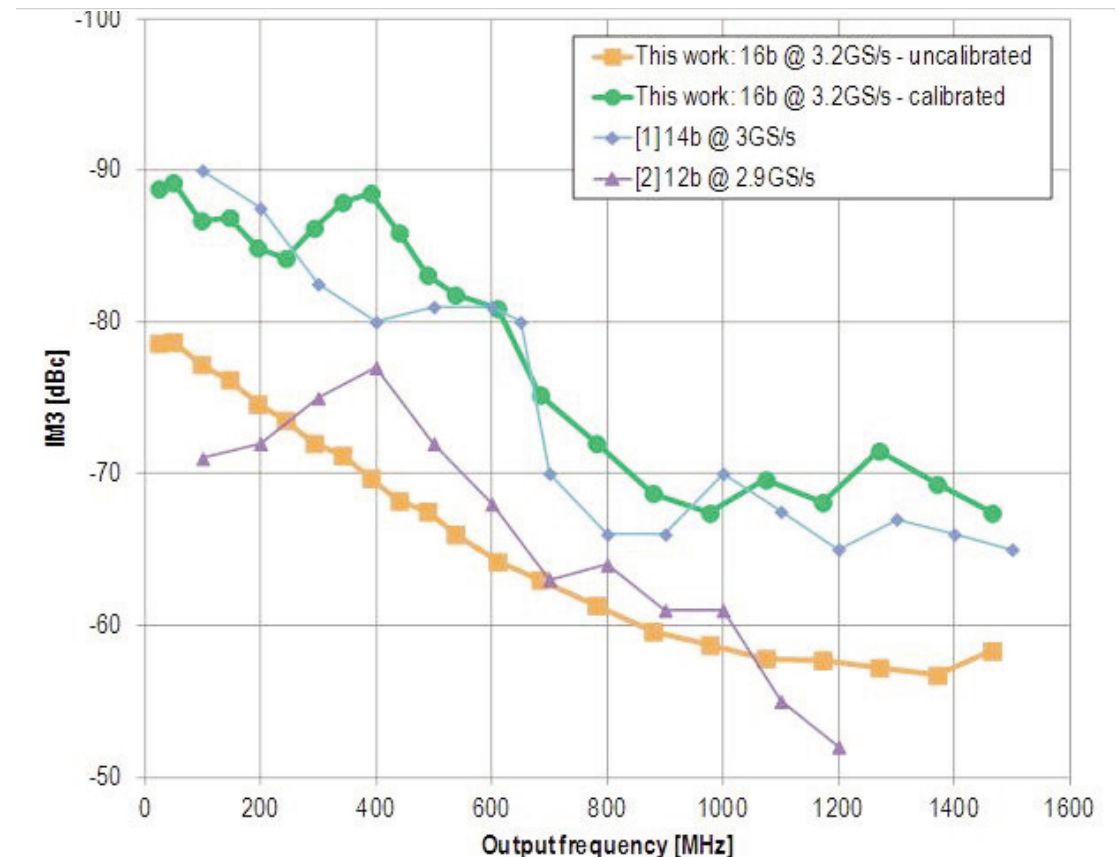
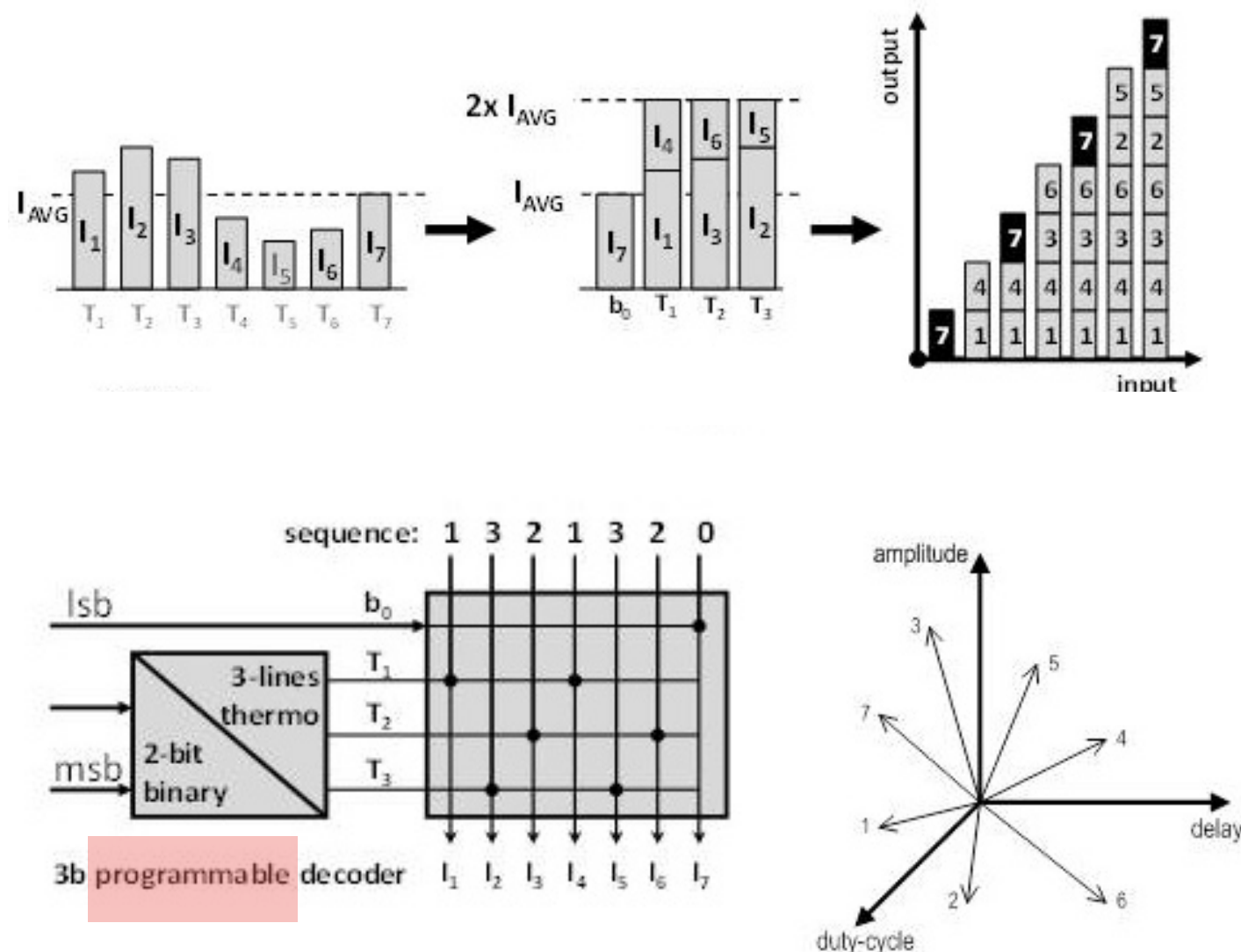


Figure 11.7.4: IM3 versus output frequency with and without 3D-SC calibration compared to state-of-the-art multi-GS/s CMOS DACs.

- Rather than random combination, select best combo
- Several dimensions (amplitude, delay, duty cycle)

Summary

- Digital techniques highly useful to compensate for many kinds of conversion errors
 - Per sample and/or on average
 - Performance far beyond what is possible with “ordinary” techniques
- Digital gets cheaper over time (Moore!)
- Suggests trend towards simpler analog and more sophisticated digital processing (cf. Murmann)