

# Noise shaping

DAT116, 20181217

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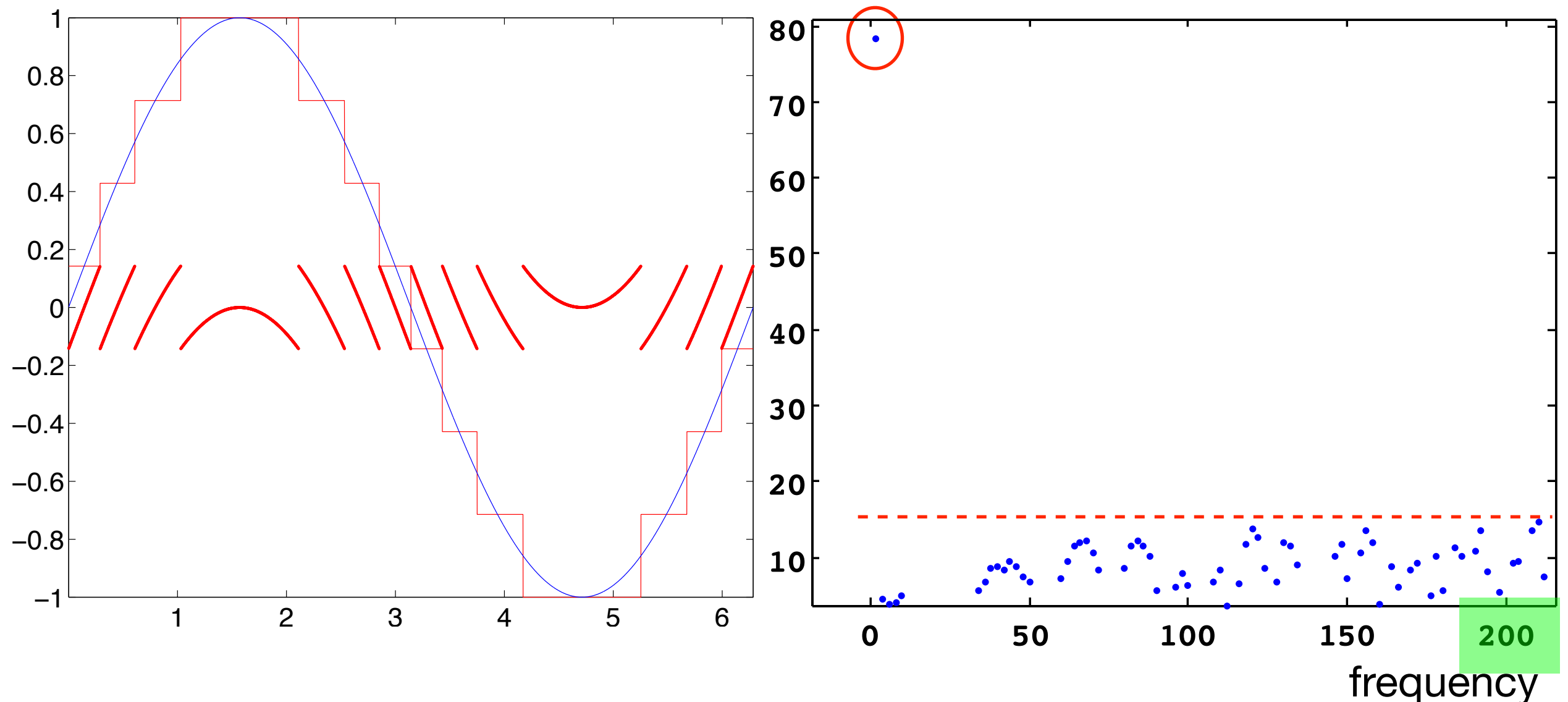
# What?

- Improve SNDR beyond  $6.02 N + 1.76$  dB

# How?

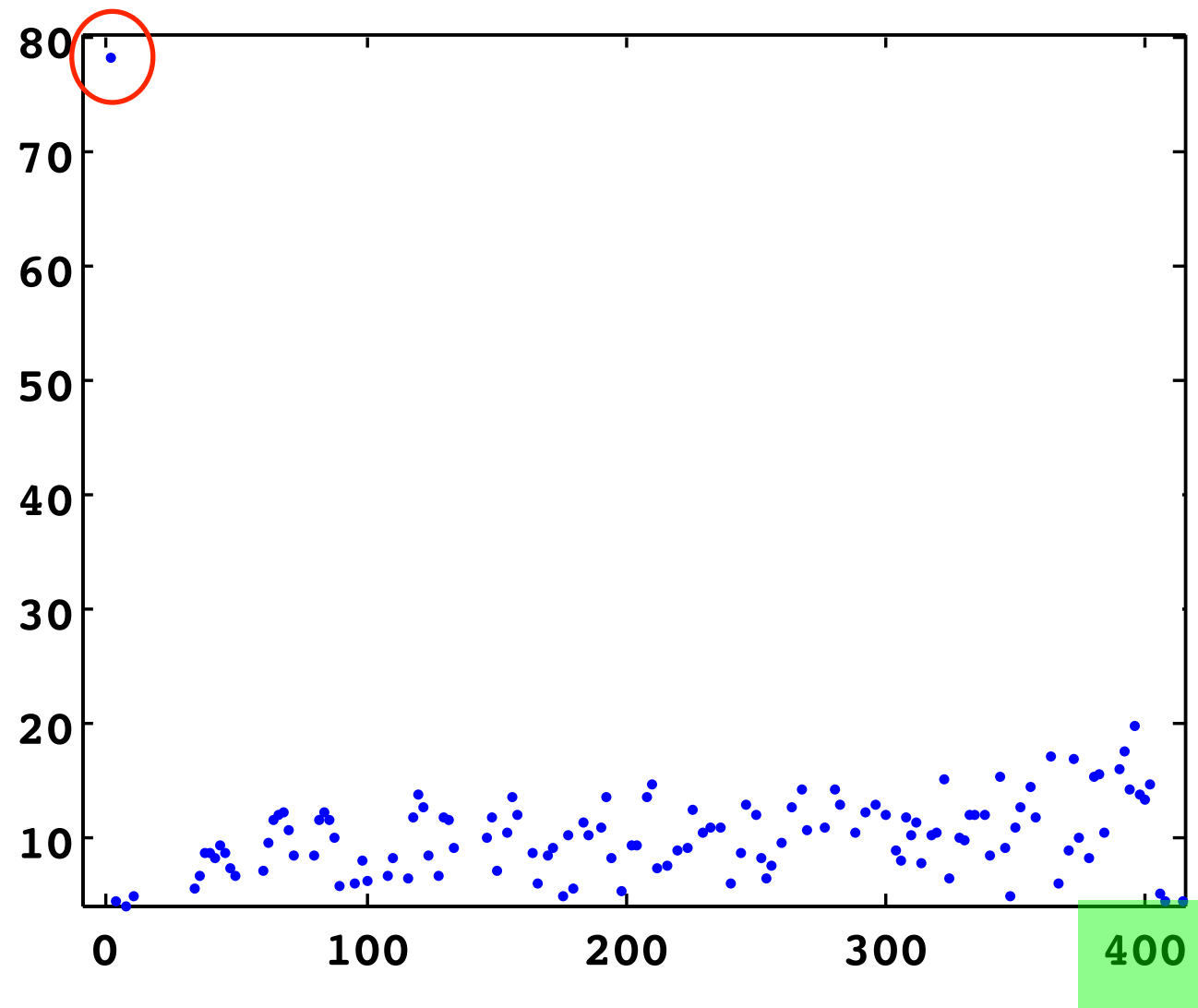
- Force errors out of band-of-interest; filter

# Quantization with Nyquist sampling



- $\text{SNR} = 6.02 N + 1.76 \text{ dB}$  (full-scale sinewave input)
- Noise power independent of sample rate

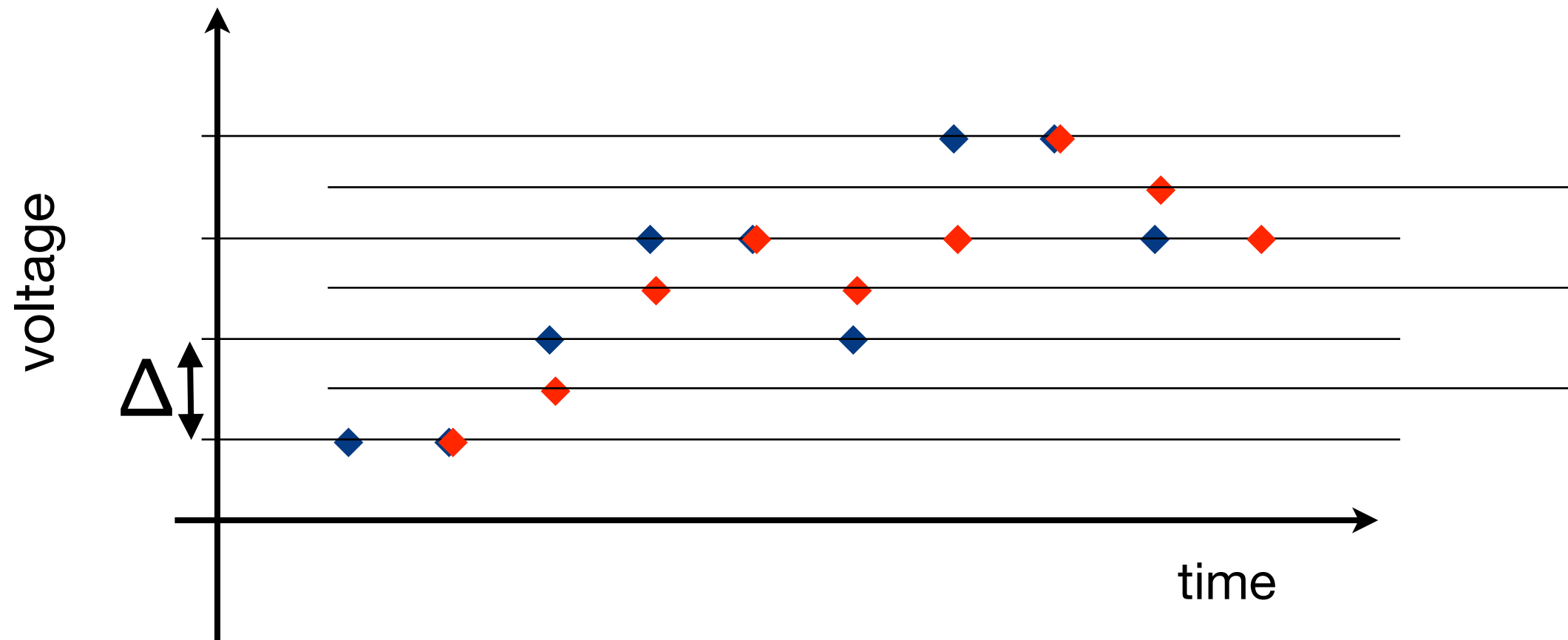
# Oversample by factor 2



Here,  $\text{OSR} = 2$   
Design  
parameter!

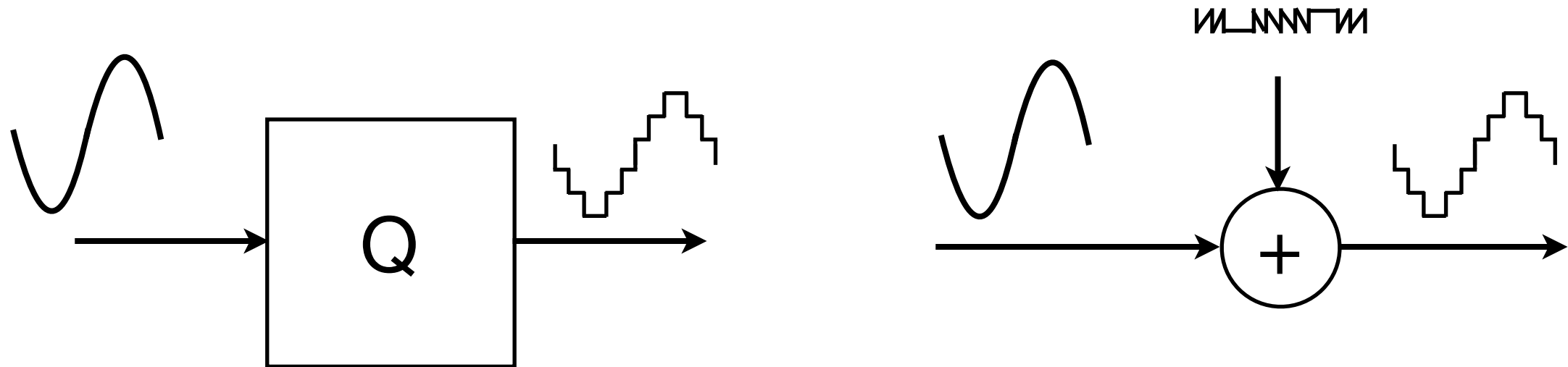
- Same total noise power ( $\Delta^2/12$ ), but twice the frequency bins
- Post-sampling low-pass DT filter; removes half the noise power
- Then downsample by 2x by dropping every other sample
- Improve SNR by **3dB** per factor 2 of oversampling! Yay!

# Relation with resolution



- Intuitively:
  - Filter by  $(1 + z^{-1}) / 2$  [simplest LP]
  - “New” “levels” introduced
  - Reduced  $\Delta$ , so reduced noise!

# Linear converter model

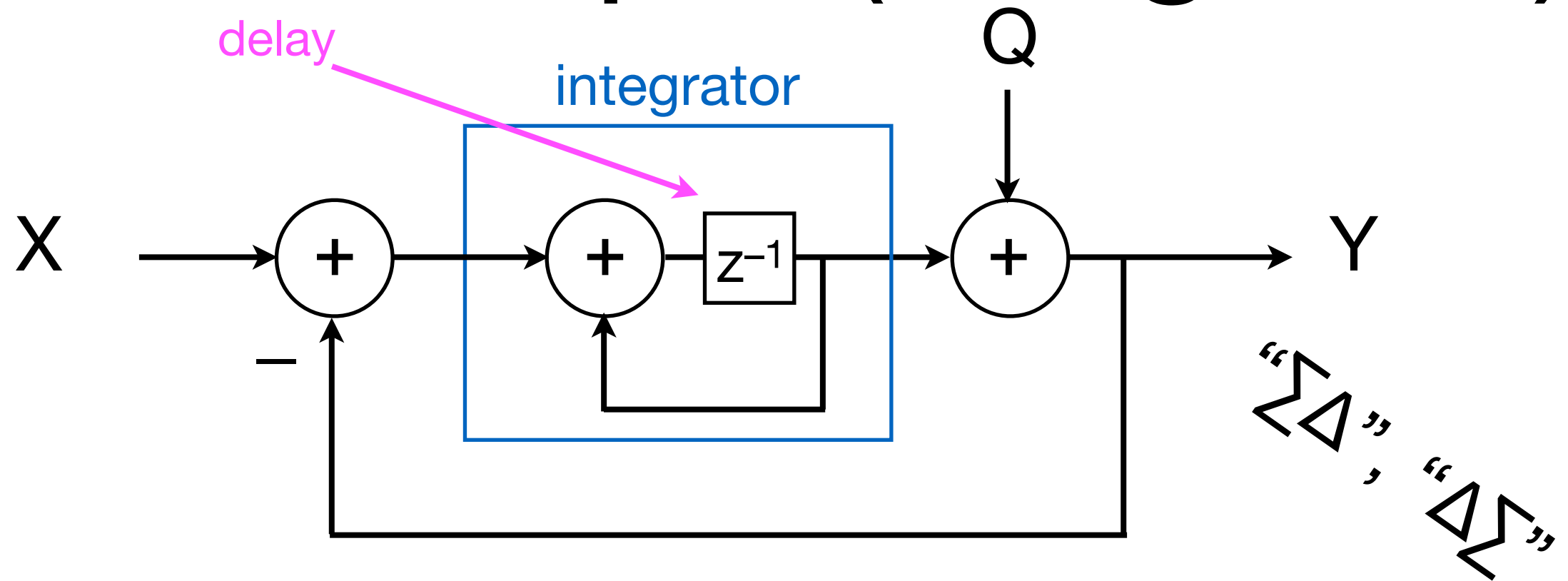


- Quantization is a non-linear process
- May be modelled as noise addition
  - Linear system!
- Assume added noise is white and uncorrelated with signal
  - OK if resolution is high

# Noise shaping

- Idea: use oversampling and push more of the noise out of signal band!
- Feedback loop w/ linear filter
- Use digital post-filter (DT!) to suppress out-of-band noise
  - More noise removed than with “straight” oversampling
- SNR improves more than 3dB per x2 !
  - More effective for larger oversampling ratios

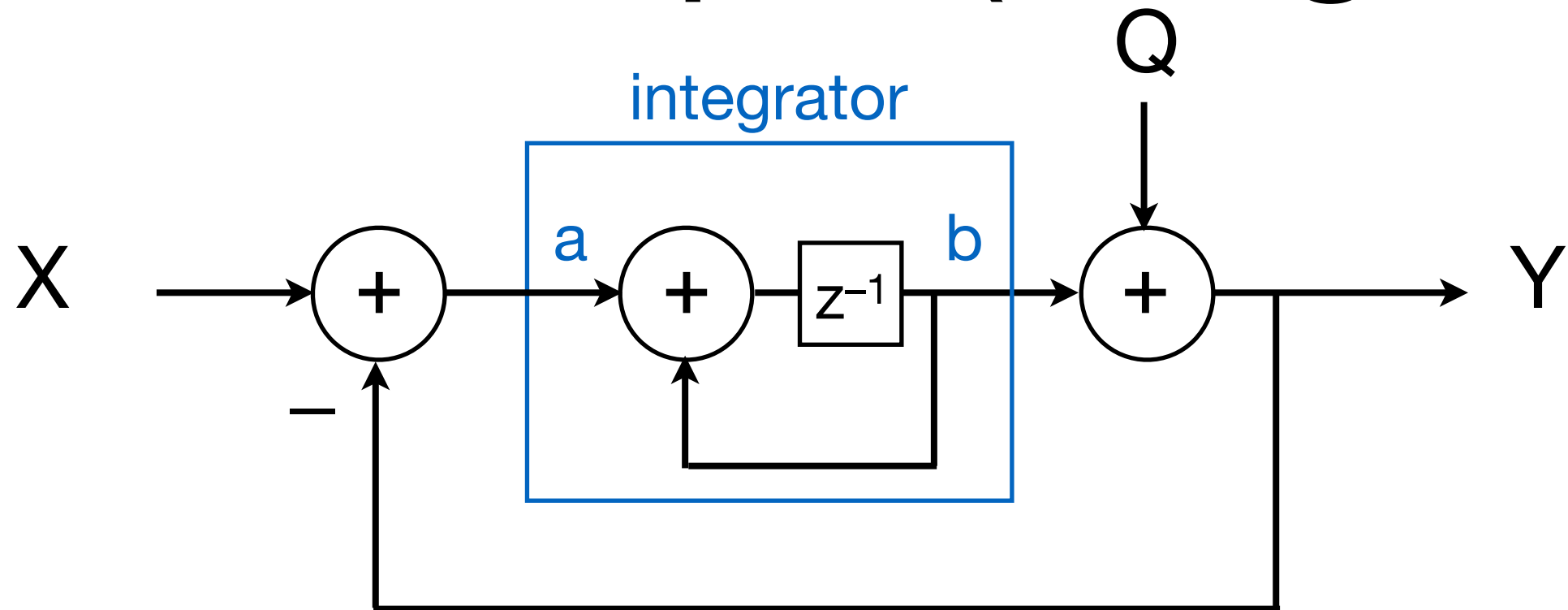
# Simple example (integrator)



- Linear model: superposition, transfer functions
  - $X$  to  $Y$  (Signal Transfer Function, STF)
  - $Q$  to  $Y$  (Noise Transfer Function, NTF)
- Use  $z$  transform



# Simple example (integrator)



integrator:  $b = z^{-1} (a + b)$  ;  $b (1 - z^{-1}) = a z^{-1}$

$$H(z) = b / a = z^{-1} / (1 - z^{-1})$$

$$Y = Q + (X - Y) z^{-1} / (1 - z^{-1})$$

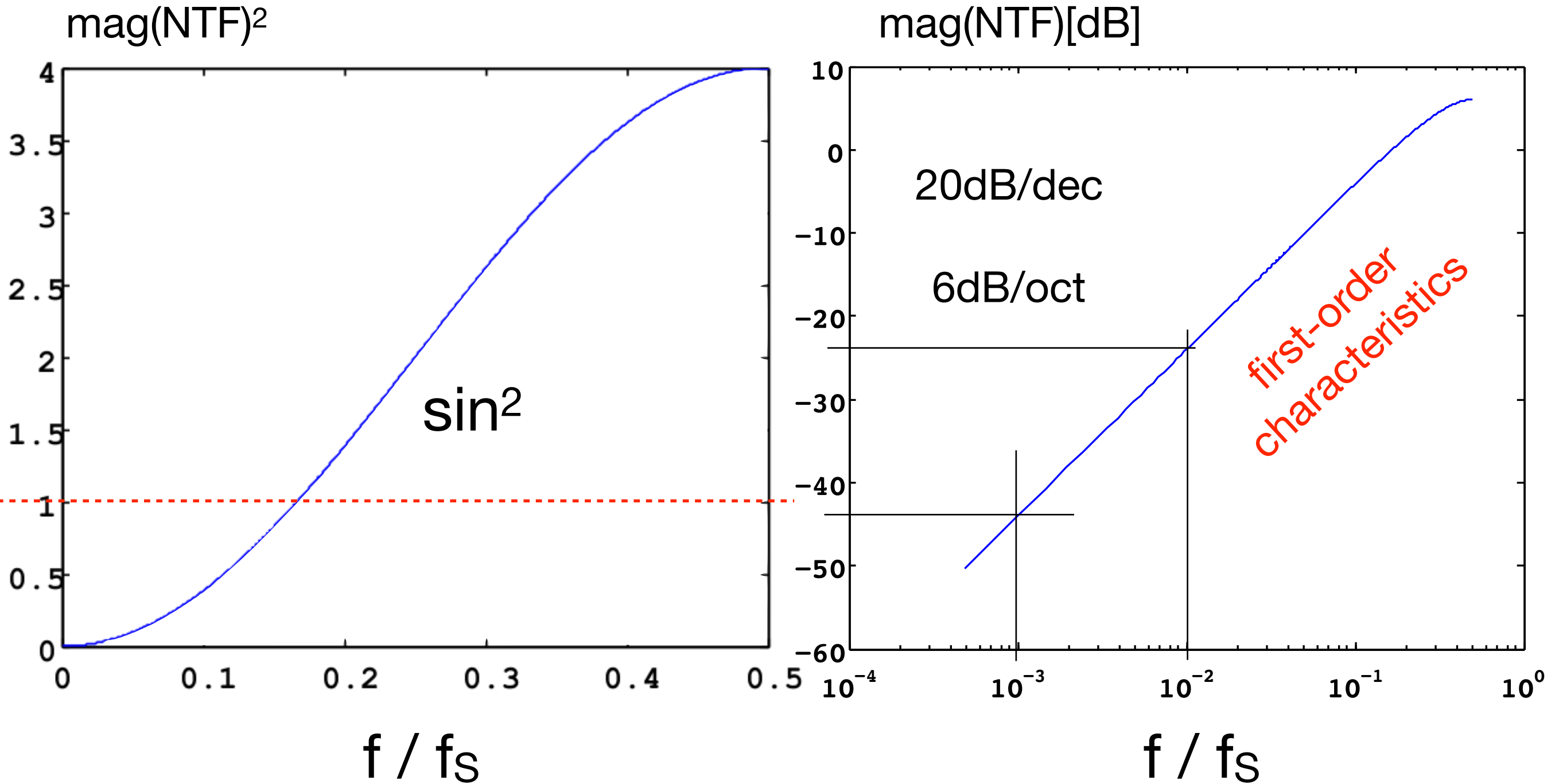
$$Y = Q + X z^{-1} / (1 - z^{-1}) - Y z^{-1} / (1 - z^{-1})$$

$$Y = (1 - z^{-1}) Q + z^{-1} X$$

STF:  $z^{-1}$   
delay

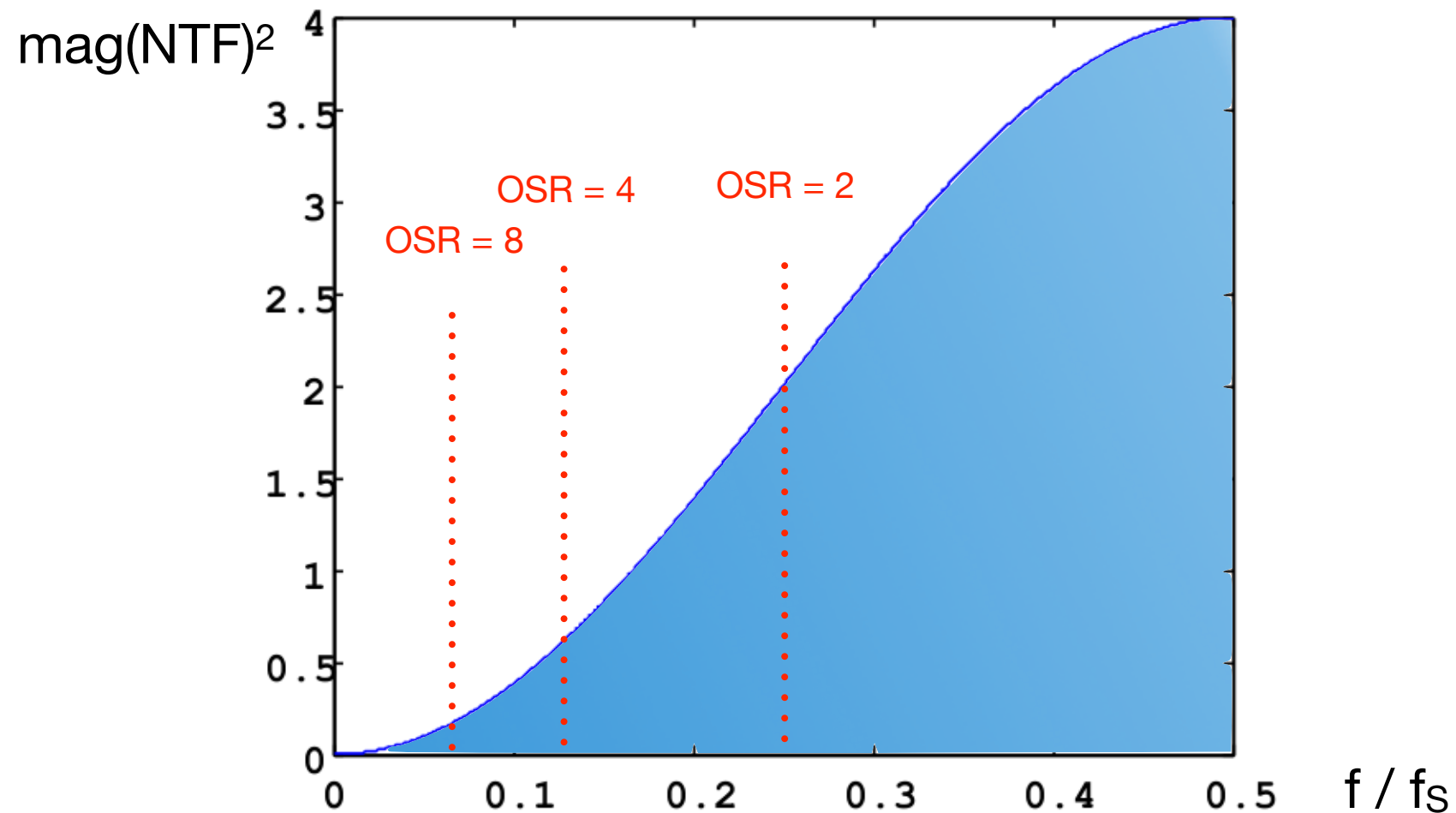
NTF:  $(1 - z^{-1})$   
highpass

# NTF plots



Total noise power is increased!

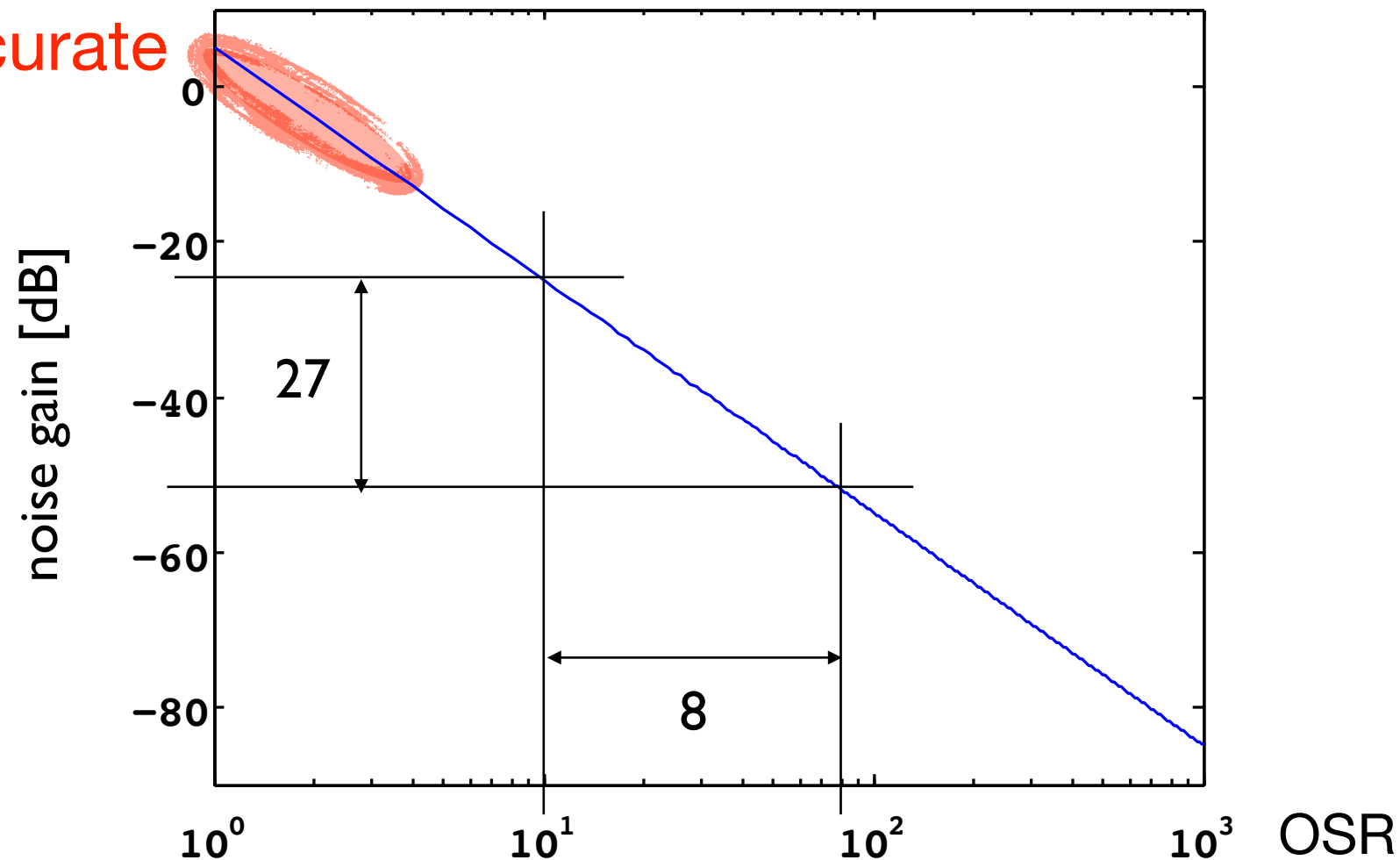
# ...but filtering saves us



- Small  $x$ :  $\sin x \approx x$ ;  $\sin^2 x \approx x^2$
- $\int x^2 dx \sim x^3$  ; remaining noise  $\sim \text{OSR}^{-3}$

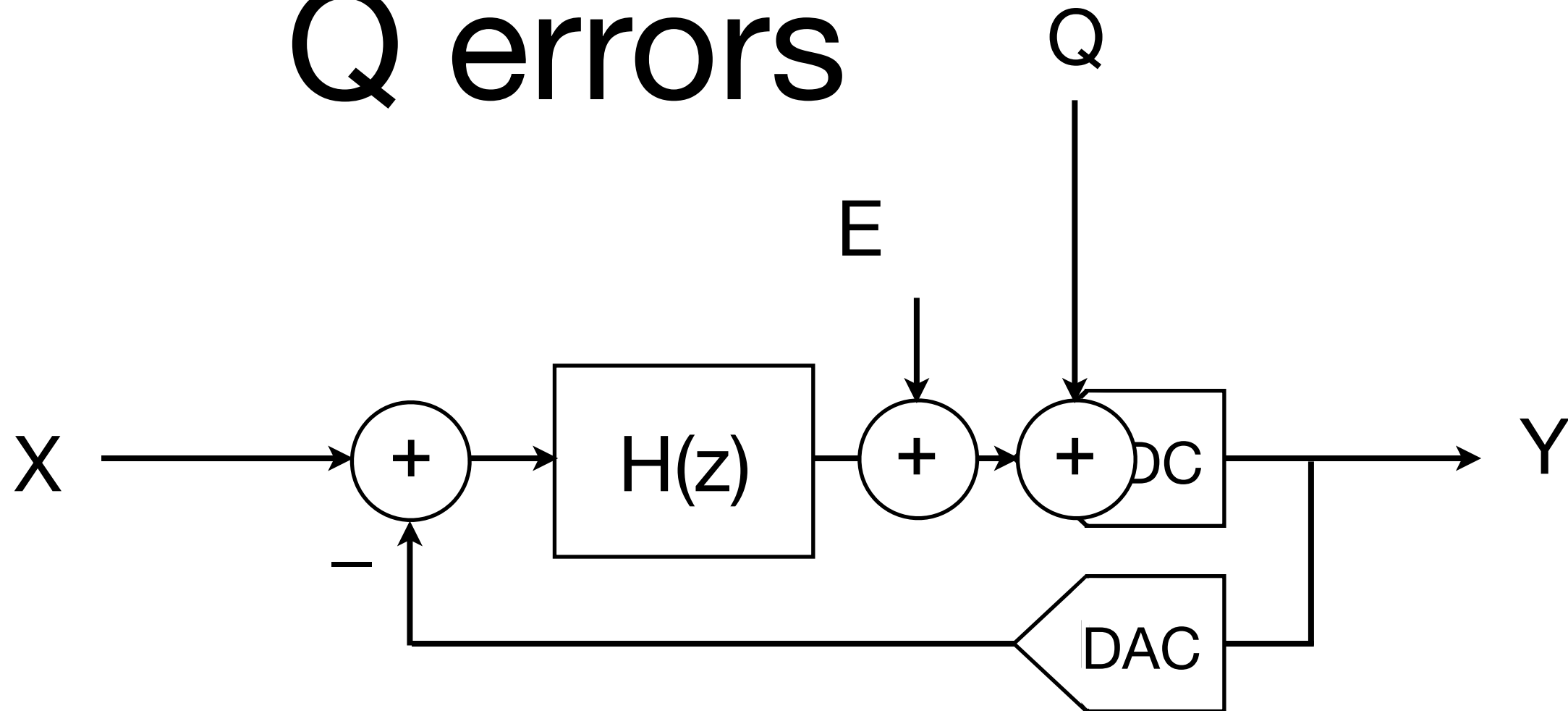
# SNR vs oversampling ratio?

not accurate



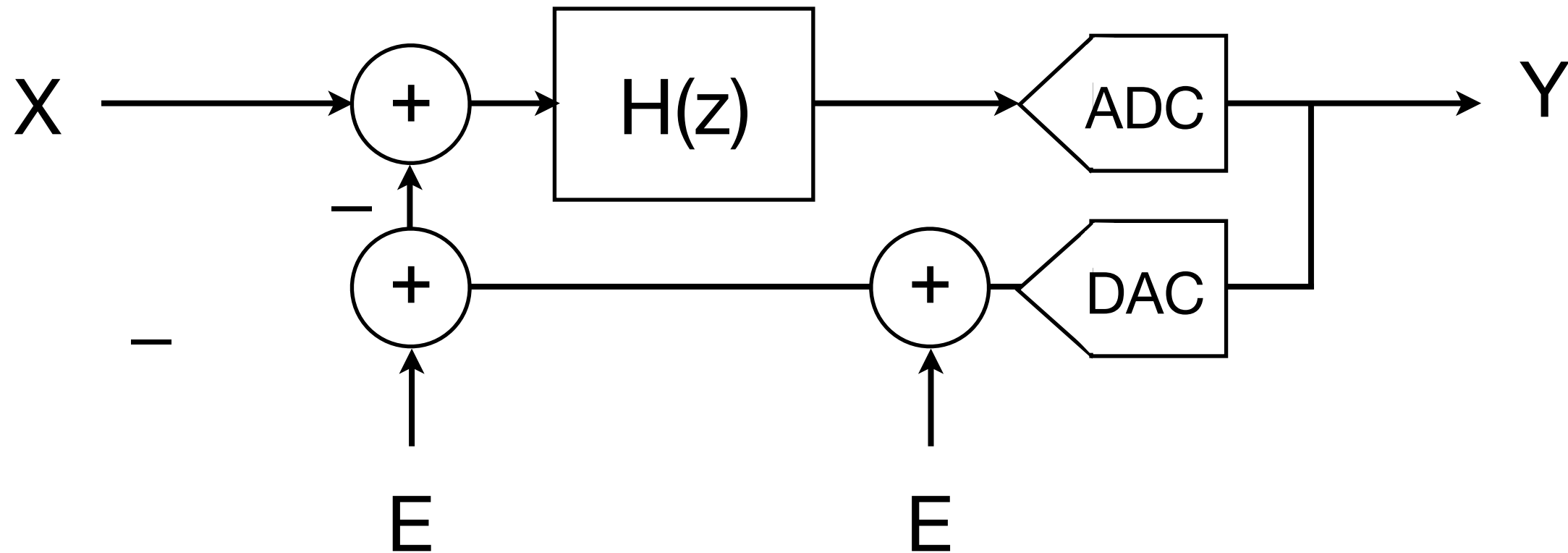
- Assume OSR is  $M$  (reasonably large)
- Then part of noise which falls in passband is  $(\pi^2 / 3) M^{-3}$
- 9 dB SNR improvement for each doubling of OSR

# Q errors



- Additional quantizer errors (INL, DNL) indistinguishable from “ideal” quantization noise
- Will be shaped out of band of interest
- Low-precision quantizer usable!

# DAC errors



- DAC errors indistinguishable from input
- DAC precision critical!

# $\Sigma\Delta$ features

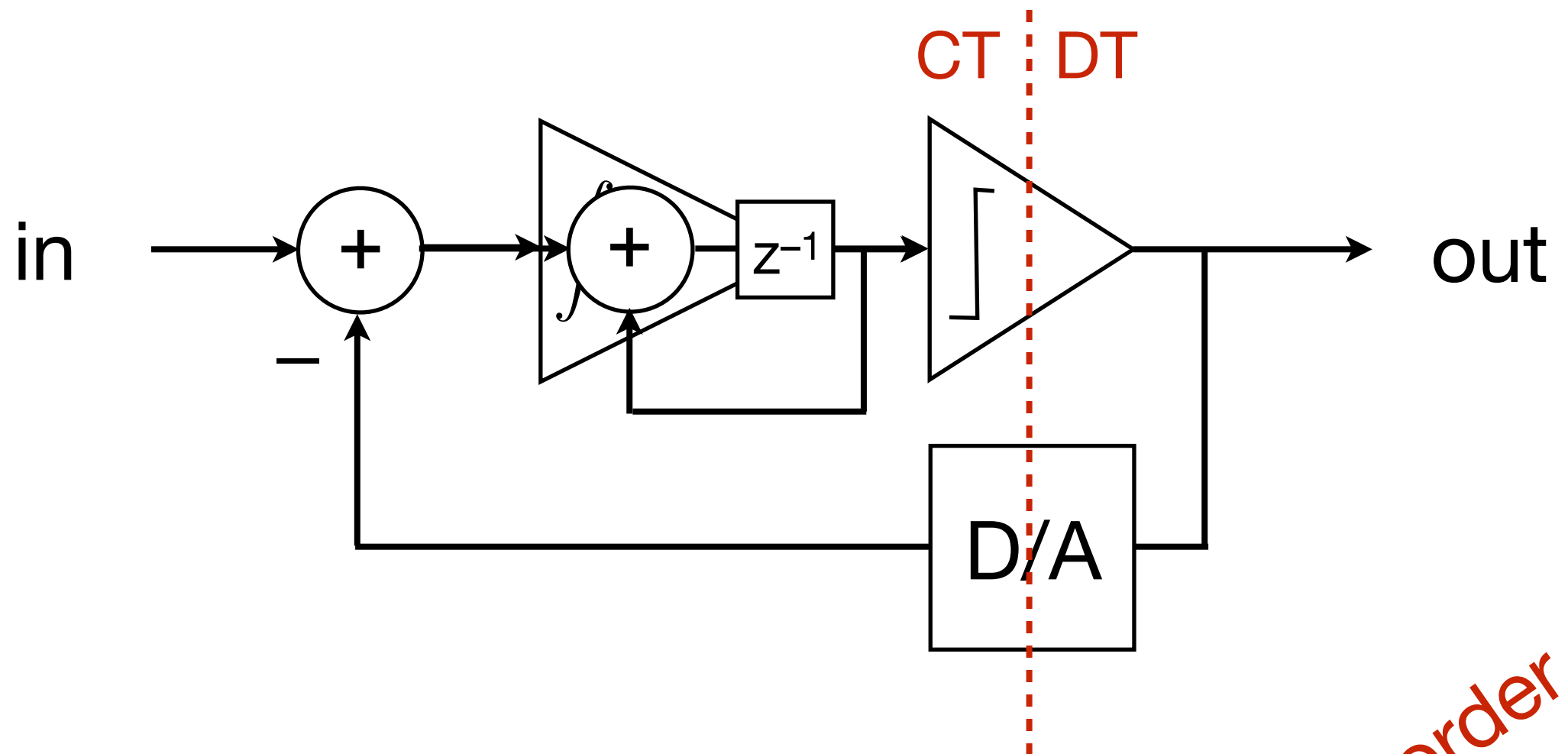
- + Possible to improve SNR beyond quantizer capabilities
  - Get away with lower-precision quantizer for given SNR
  - Easy to implement in standard CMOS
- Low signal bandwidth
- High-speed circuits needed
- Higher latency due to feedback loop
- $\pm$  No direct relation between input and output

# Extreme $\Sigma\Delta$ : 1-bit quantizer

- Logical extreme 😊
- No DAC, ADC nonlinearity to worry about
- Needs large OSR for useful performance
  - “Base” SNR is less than 8dB!
- Some assumptions violated!
- Linear model not dependable



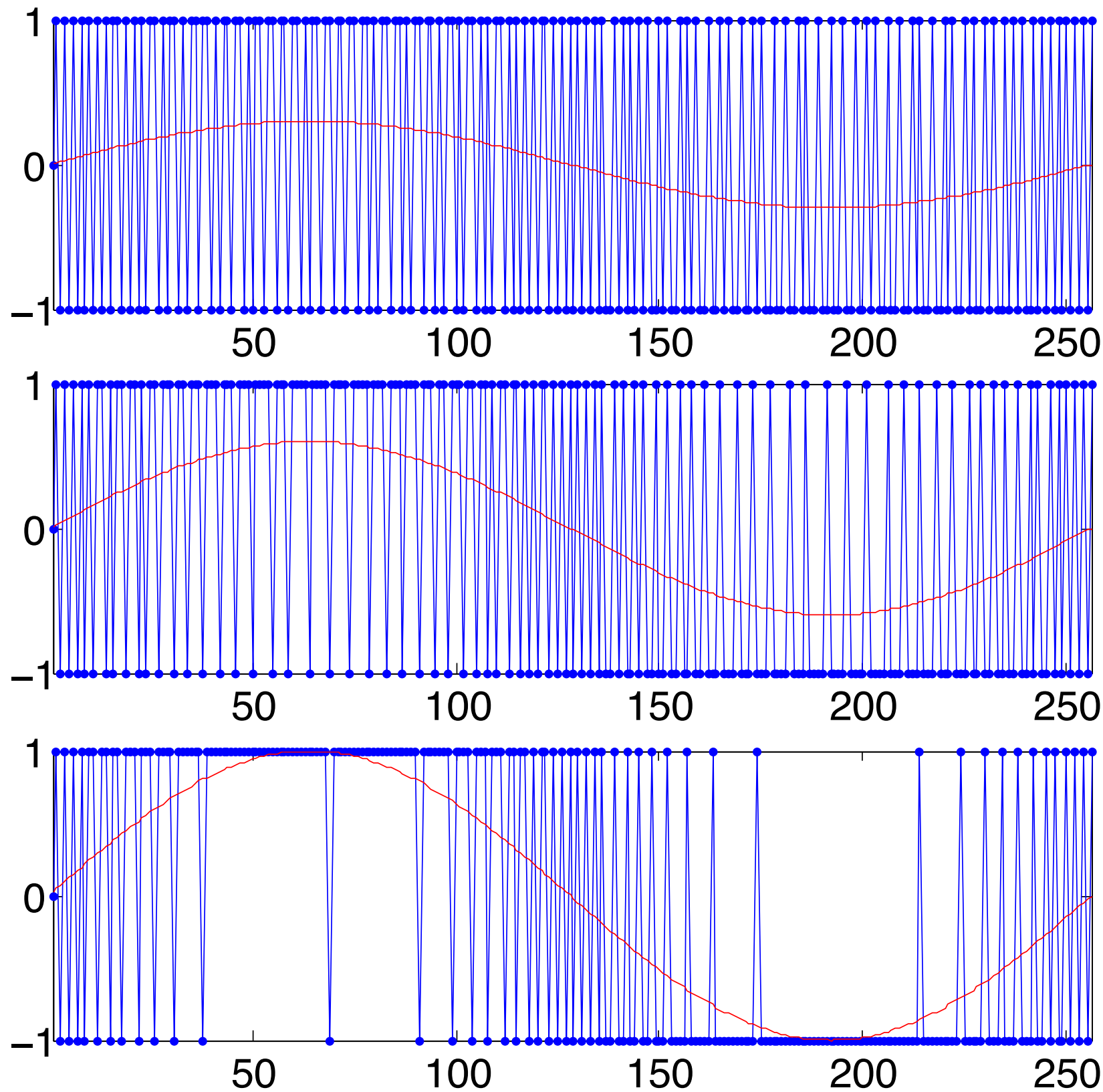
# One-bit block diagram



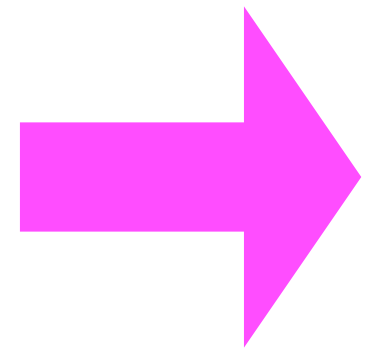
- Integrator, comparator, 1-bit D/A
- Error is integrated, compensated for
- Very simple hardware!

CT/DT border  
chosen per  
application

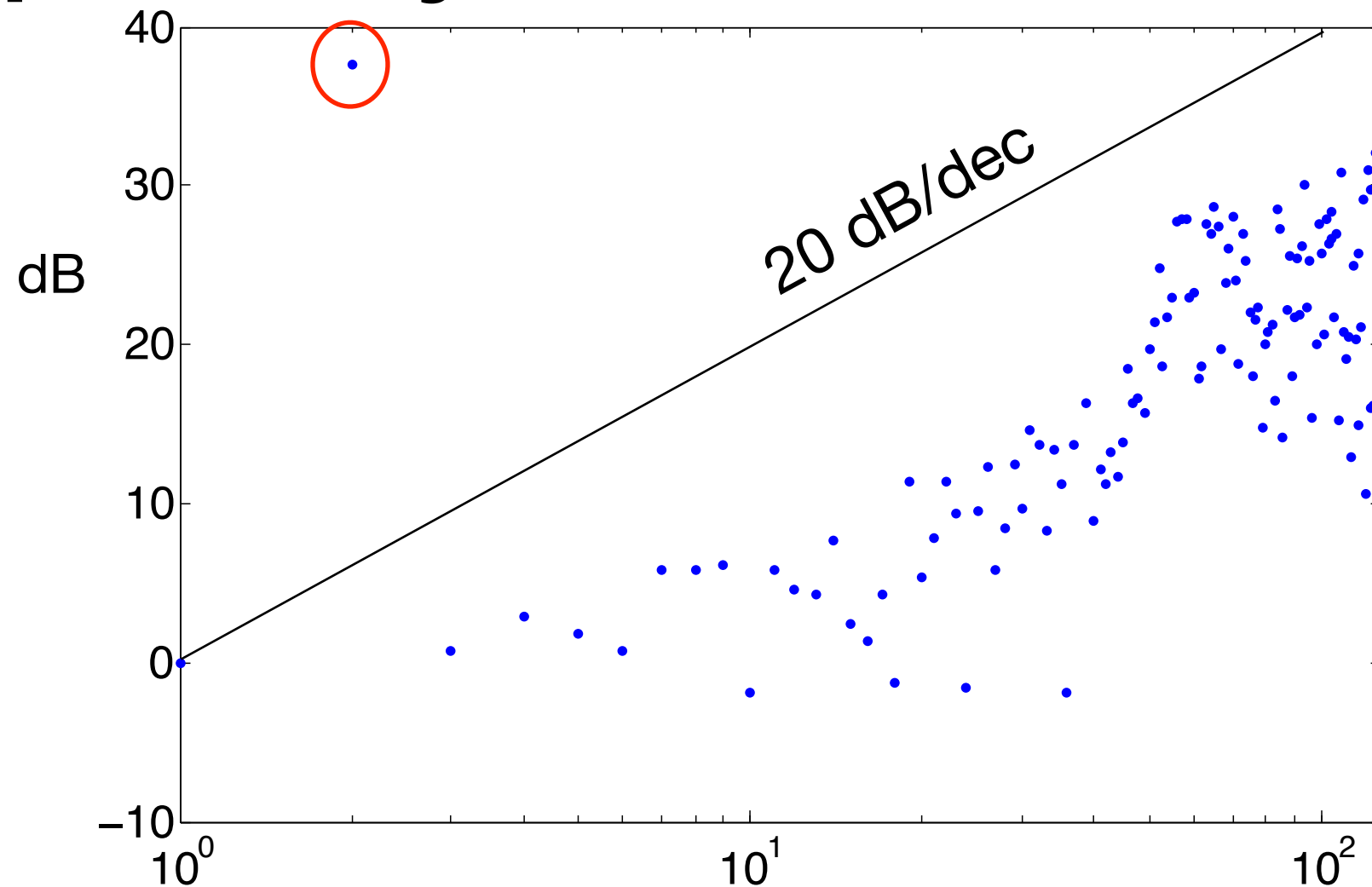
# Time-domain behavior



*Simulated  
behavior*

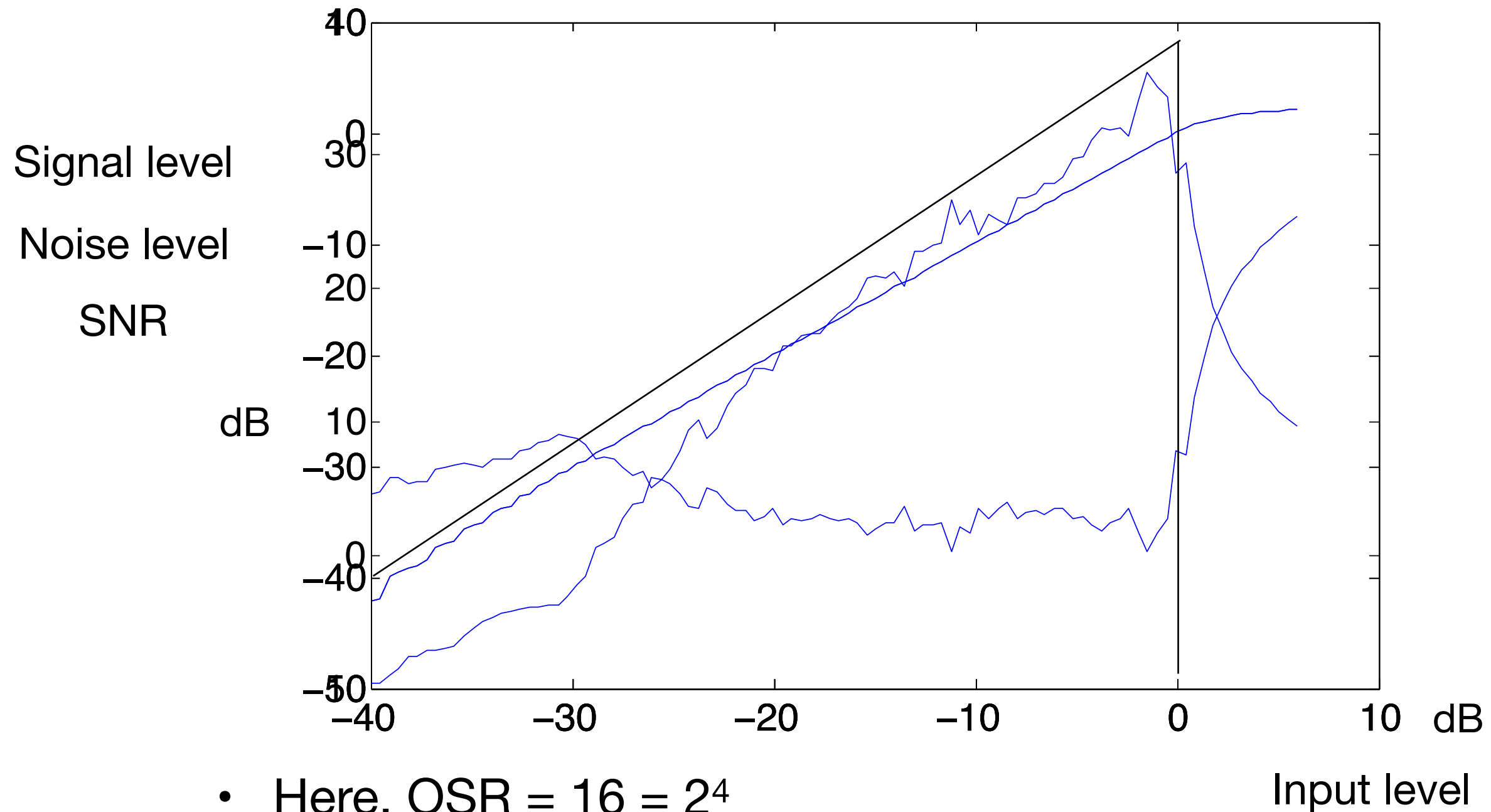


# Frequency-domain behavior



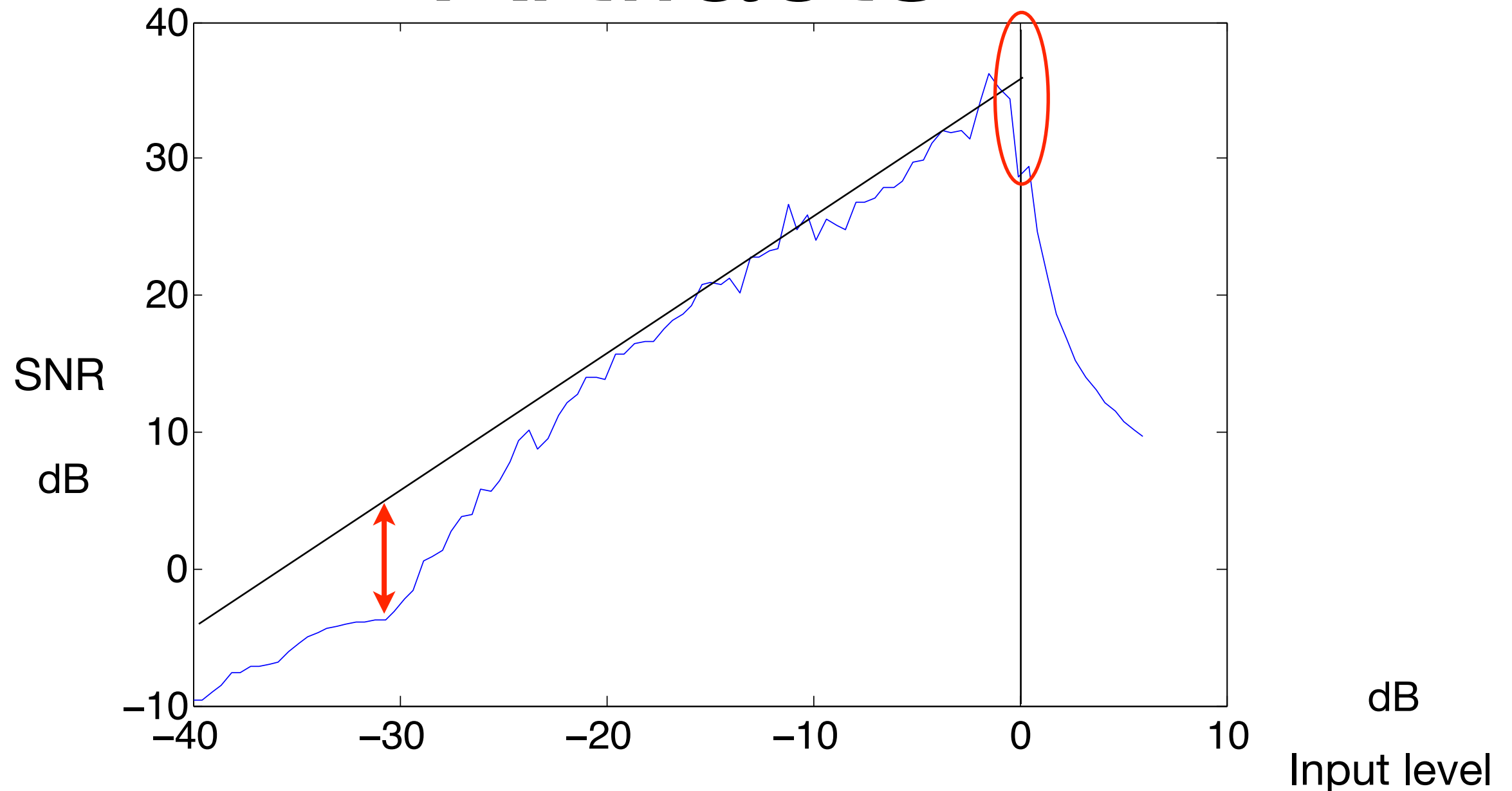
- Obvious high-pass noise character!
- Approximates first-order characteristics

# S, N, SNR vs input level



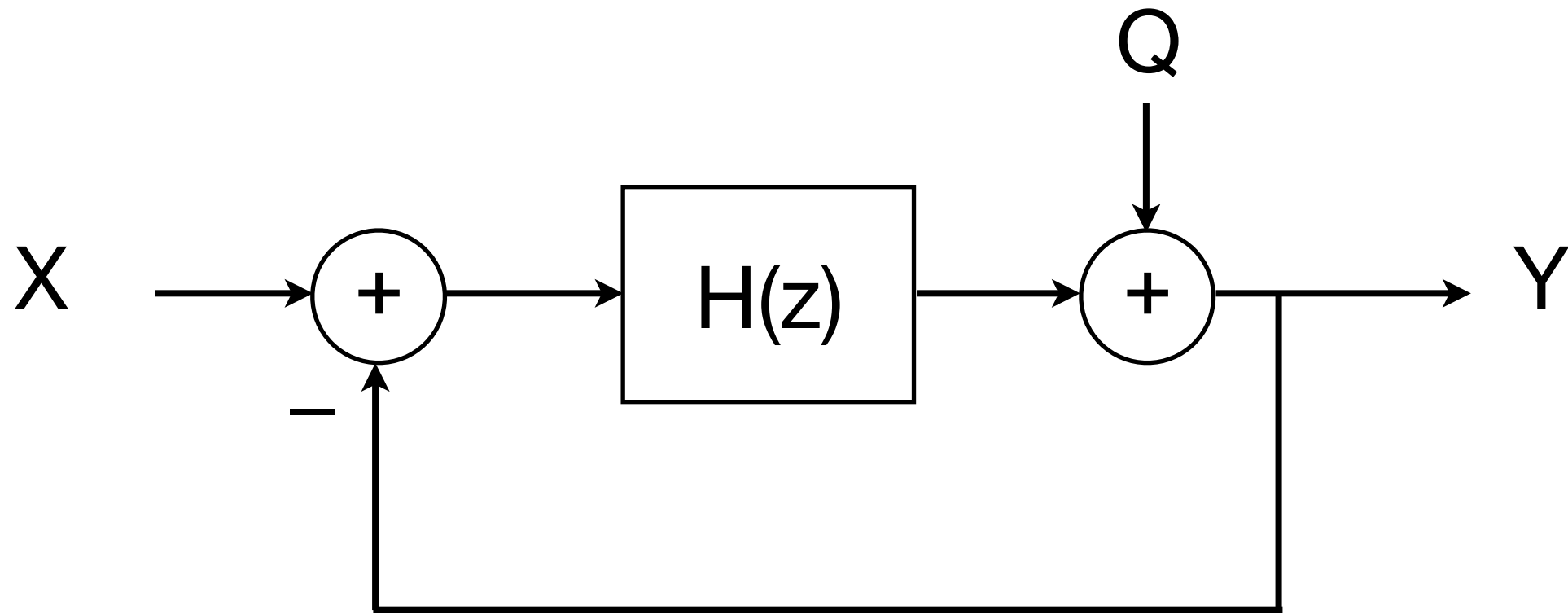
- Here,  $\text{OSR} = 16 = 2^4$
- Theoretically  $6 + 2 - 5 + 4 \cdot 9 \text{ dB} = 39 \text{ dB}$
- Worse in practice

# Artifacts



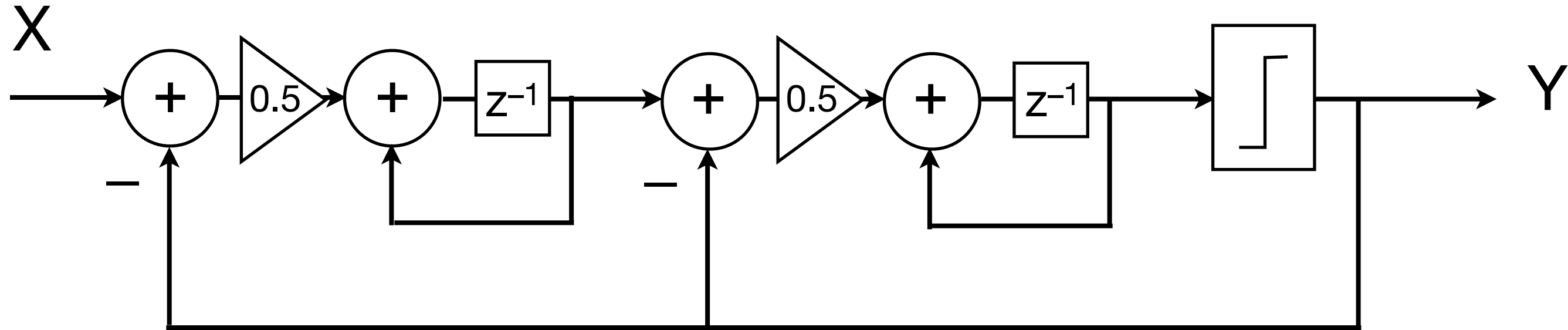
- SNR starts falling before input reaches full scale
- Extra noise at low input levels
- Limit-cycle “tones” (as will be seen in lab)

# Higher loop orders



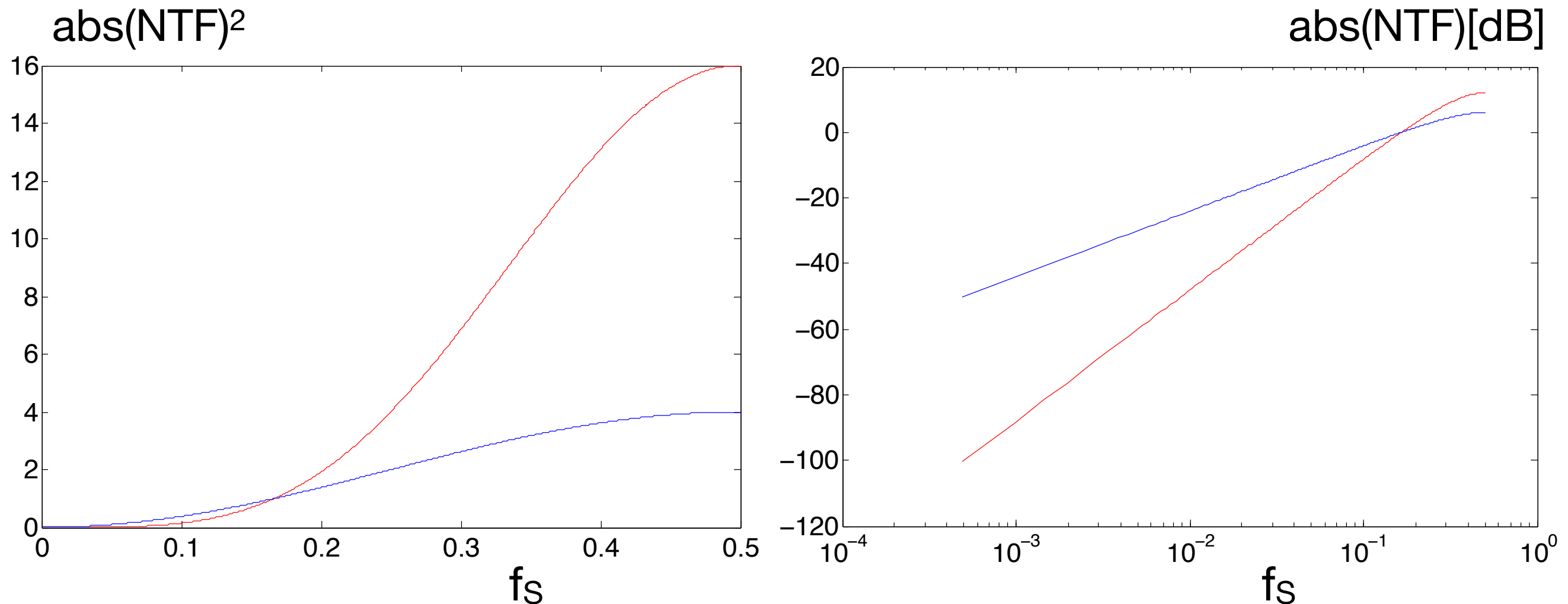
- Integrator = first order  $H(z)$
- Possible to use higher-order  $H(z)$ 
  - Push out more of the noise!

# 2nd-order $\Sigma\Delta$ loop



- $Y = X \cdot z^{-2} + Q (1-z^{-1})^2$
- Note squares!
- Simple loop structure; many alternatives exist

# Ideal noise shaping

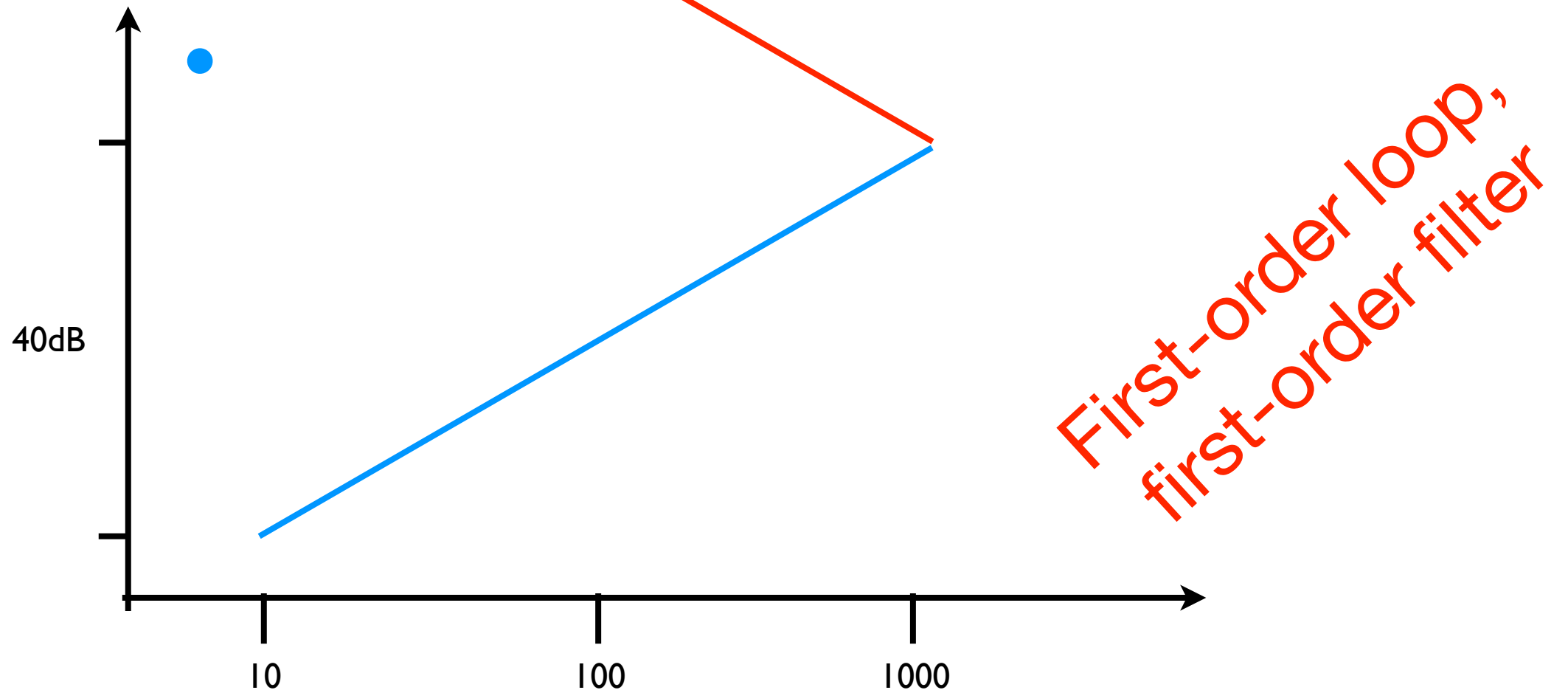


- Better suppression of in-band noise, steeper rise
- Higher total noise gain than for 1st order
- 15dB SNR improvement per doubling of OSR

*Higher orders possible!*



# Digital-filter steepness?



- Noise rises by 20 dB / decade per loop order
- Filter must suppress noise at least as steeply!
- $\geq 1$ st order filter for 1st order loop, etc

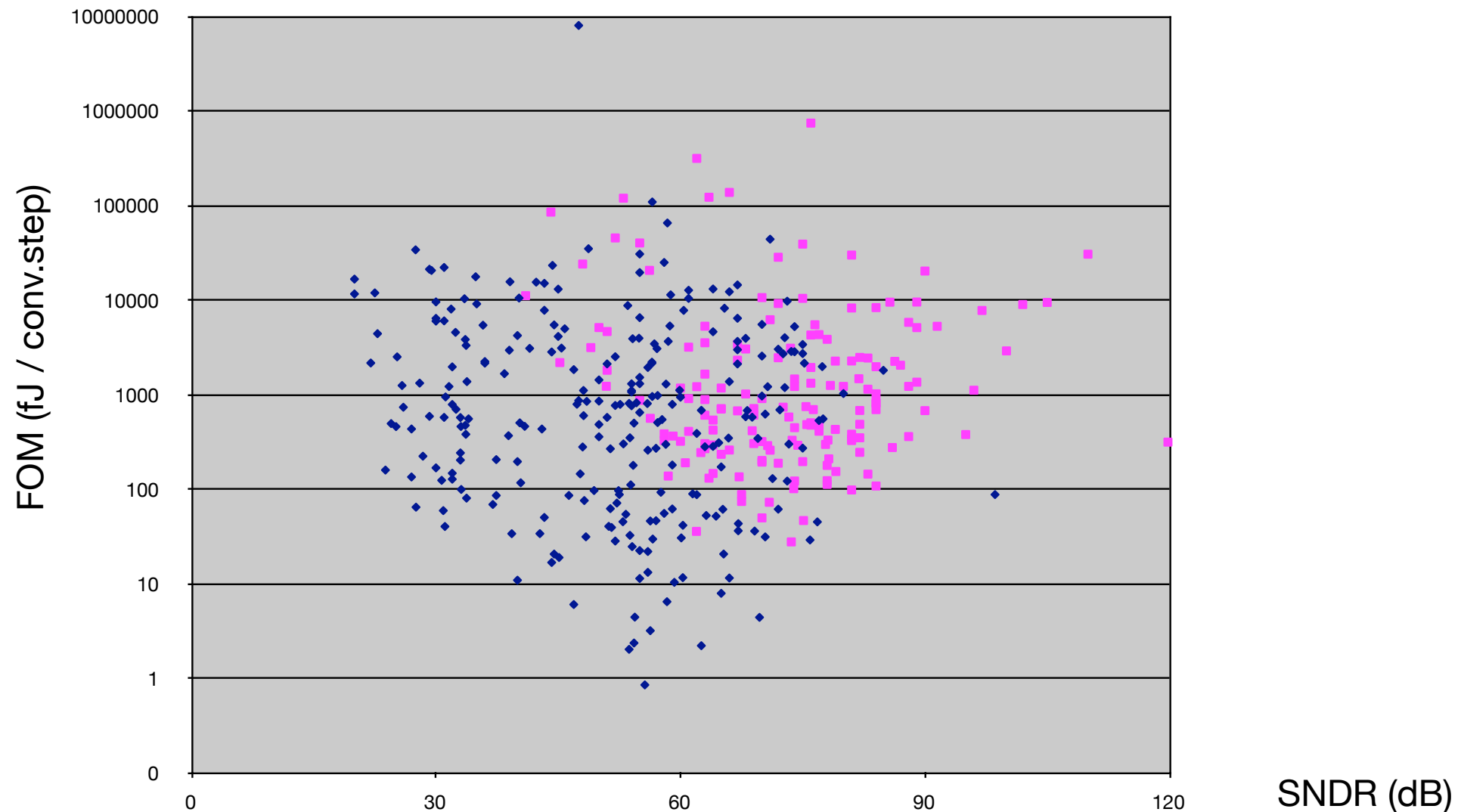
# Sample rate reduction

- After low-pass filtering, typically reduce sample rate to Nyquist rate
  - For  $\text{OSR} = N$ , drop  $N-1$  out of  $N$  samples
  - ... or rather: don't even compute them in filter ...
- Word length increase in filter
  - Averaging!
  - Longer words needed to support SNR

# $\Sigma\Delta$ design space

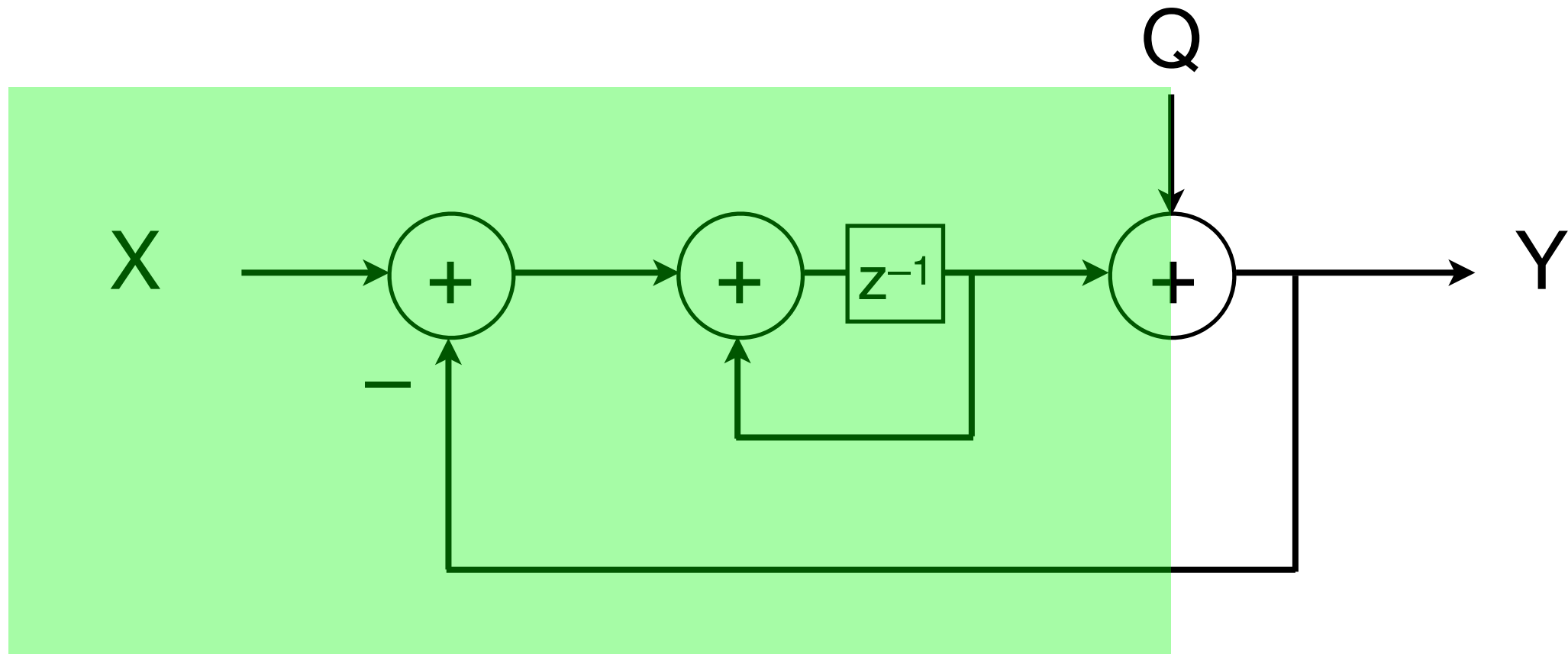
- Three ways to increase SNR:
  - Higher “core quantizer” resolution
  - Higher OSR
  - Better loop filter (higher order, better pole/zero placement)
- Stability issues for filter orders  $> 2$ 
  - Possible to manage

# When useful?



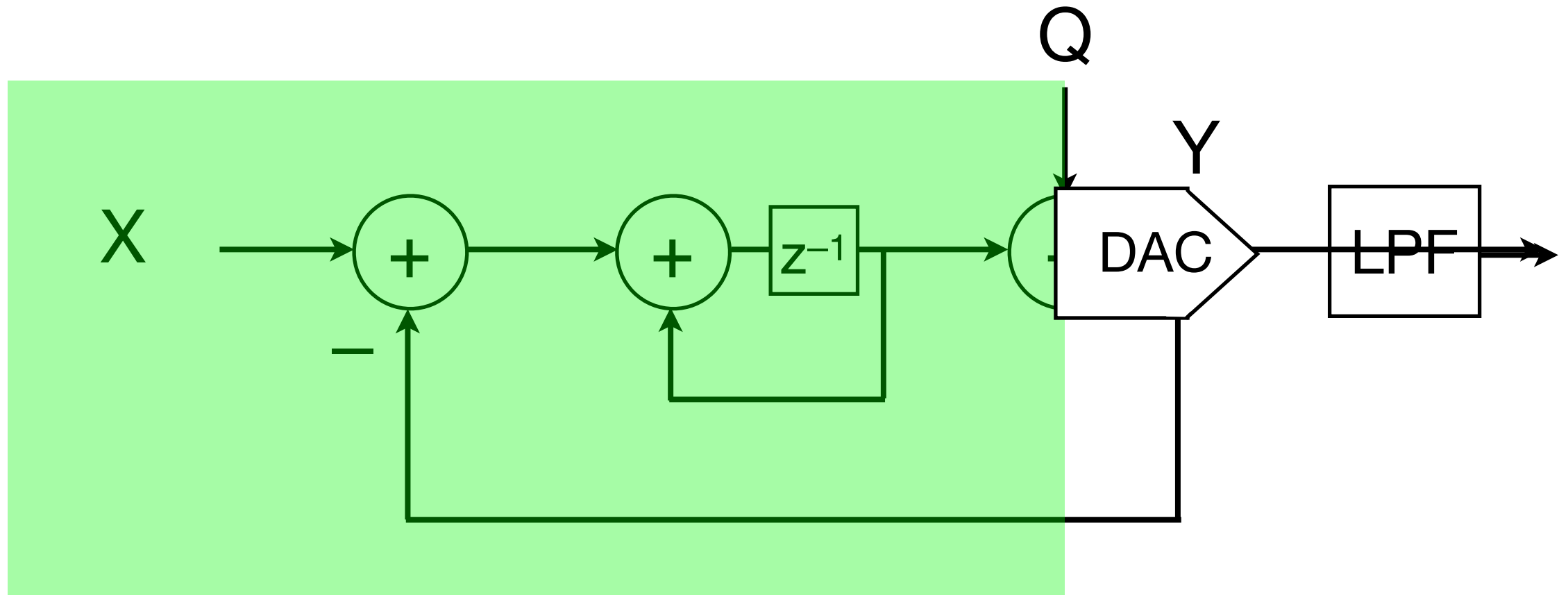
- Magenta dots for oversampled ADCs
  - High SNDRs, not the very best FoMs
  - ... and obviously not the highest signal bandwidths...

# $\Sigma\Delta$ DAC



- In ADC, green parts analog
- What if digital (high-resolution) instead?
  - Loop still works!
- Full theory still applicable!

# $\Sigma\Delta$ DAC



- Pre-processing for lower-precision DAC
  - $X$  higher resolution than  $Y$
  - $Y$  at higher sample rate
- Quantization now corresponds to rounding / truncation
- $Y$  may be a 1-bit signal (much upsampling needed)

# Summary

- Noise shaping + filtering enables higher SNR than quantizer alone could give
  - High-pass noise filter not the only option!
- Simpler analog at cost of higher sample rate
- Feedback loop neutralizes (most...) errors
- DT lowpass filter (digital) for downsampling / reconstruction
- Also useful as pre-processing for low-resolution DACs